Financial Markets, the Real Economy, and Self-Fulfilling Uncertainties*

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Abstract

We develop a model of informational interdependence between financial markets and the real economy, linking economic uncertainty to information production and aggregate economic activities in general equilibrium. The *mutual* learning between financial markets and the real economy creates a strategic complementarity in their information production, leading to self-fulfilling surges in economic uncertainties. In a dynamic setting, our model characterizes self-fulfilling uncertainty traps with two steady-state equilibria and a two-stage economic crisis in transitional dynamics.
Uncertainty in both financial markets and the real economy rises sharply during recessions. The recent financial crisis of 2007-2009 presented one of the most striking episodes of such heightened uncertainty. Financial market uncertainty, measured by the VIX index, jumped by an astonishing 313% in the Great Recession. The increase in measured real economic uncertainty was equally astounding. For instance, macroeconomic uncertainty measured in Jurado, Ludvigson, and Ng (2015) almost doubled, and Bloom et al. (2012) report a 152% increase in micro-level real uncertainty as measured by the firm-level dispersion of output. What causes such sudden spikes in uncertainty? Why do financial uncertainty and real uncertainty move together? And why do they rise sharply in recessions? These questions are of central importance to understanding the interaction between financial markets and the real economy. In this paper we provide a theoretical framework for addressing these questions.

Specifically, we develop a model of informational interdependence between financial markets and the real economy, linking uncertainty to information production (or acquisition) and aggregate economic activities. As the starting point of our theory, we argue that there exists mutual learning between financial markets and the real economy. Their joint information productions determine both allocative efficiency in the real sector and market efficiency in the financial sector. As an example, oil producing companies scrutinize oil futures prices when making their production decisions, while the financial market studies the financial reports of these producing companies to learn information when trading on oil futures. This mutual learning creates a strategic complementarity between information production in the financial sector and information production in the real sector. A self-fulfilling surge in financial uncertainty and real uncertainty can naturally arise when both sides produce little information in anticipation of the other producing little information. At the same time, aggregate output falls as real allocative efficiency deteriorates.

We formalize the idea in an extended Grossman-Stiglitz (1980) model. Our key innovation is that we introduce a real sector along the lines of Dixit-Stiglitz (1977) — in our framework, firms have to make investment decisions under imperfect information about two dimensions of uncertainty: their idiosyncratic productivity (supply) and demand shocks. We start with one firm and one financial market in our baseline partial equilibrium model for a given level of aggregate output. To reduce uncertainty, the firm can learn about its productivity shock by incurring a cost, but it has to infer its demand shock from information provided by the financial market, where speculators (or traders) have a comparative advantage in acquiring information about the demand shock. In this context, the financial price is jointly determined by the firm’s information production and thereby its disclosure about the productivity shock and the information produced by financial market speculators about the demand shock. To understand strategic complementarity between these two sources of information, first suppose that the firm makes more accurate information disclosure about its productivity shock. The reduction in uncertainty about the productivity shock attracts more
informed traders and also induces more aggressive trading of informed traders. Hence, the amount of information provided by the financial market about the demand shock increases. Conversely, suppose that for some reason the financial price becomes more informative about the demand shock. The reduction in uncertainty regarding the demand shock enables the firm to make better investment decisions and increases its profit multiplicatively for every realized productivity shock. This implies that the firm has stronger incentives to acquire information about its productivity shock.

As the firm’s marginal benefit of acquiring information depends on aggregate output (in addition to financial price informativeness), the nature of equilibrium also depends crucially on the level of aggregate output. At one extreme, when aggregate output is sufficiently high, the firm’s incentive to acquire information is already strong enough and acquiring information is a dominant strategy for the firm. The resulting equilibrium is hence unique in which the firm produces and discloses more precise information and the financial market generates a more informative price signal. As a result, both financial and real uncertainty are low. At the other extreme, when aggregate output is sufficiently low, not acquiring information is a dominant strategy for the firm. Anticipating this, speculators in the financial market also have little incentive to acquire information about the firm’s demand shock. The equilibrium is hence also unique. When aggregate output is in the intermediate range, however, the economy has two self-fulfilling equilibria. The information produced by the firm and the information generated by the financial market in one equilibrium (the “good” equilibrium) are much more precise than those in the other equilibrium (the “bad” equilibrium). Consequently, a surge in uncertainty can suddenly strike as a self-fulfilling equilibrium phenomenon.

We next extend the baseline model to a macroeconomic general equilibrium framework with aggregate production to endogenize the aggregate output. The level of economic activity and the amount of information available in the economy are thus jointly determined in general equilibrium. The final consumption good is produced with a continuum of intermediate capital goods as inputs according to a Dixit-Stiglitz production function. Each intermediate capital good is produced by one firm located on an island in the spirit of Lucas (1972). When information signals on some islands become noisier, real investment decisions on those islands become less efficient and consequently aggregate output declines. This causes the aggregate demand faced by other islands to drop. Thus, incentives to acquire information in the real sector on those other islands are also reduced, which decreases information acquisition in their financial sectors as well. Aggregate output therefore declines further, which in turn affects those islands experiencing the original shock. In short, the complementarity in goods production due to the Dixit-Stiglitz demand externality across islands generates further complementarity in information production across islands. As a result, the complementarity forces for equilibrium multiplicity are strengthened in general equilibrium. Similar to the partial equilibrium model, the economy may feature multiple (two) equilibria. In particular,
in general equilibrium, a self-fulfilling increase in uncertainty is accompanied by a reduction in investment efficiency and a decline in aggregate output.

We derive four key implications of our macroeconomic model. First, an adverse shock originating in either the real sector or the financial sector that impairs their ability to conduct information acquisition can have a large impact on the aggregate economy due to the compound feedback loops. Indeed, both aggregate investment and endogenous aggregate total-factor-productivity (TFP) are decreasing in information precision. Hence, a small shock in information acquisition cost can have a large impact on all three quantities (aggregate investment, endogenous aggregate TFP, and aggregate output) in the same direction, particularly when it triggers a self-fulfilling “bad” equilibrium.\(^1\) Second, our model jointly endogenizes the three variables — financial uncertainty, real uncertainty, and aggregate economic activity — and delivers countercyclical uncertainty as observed in the data. Third, our model provides an information contagion channel whereby a shock that directly affects only a small fraction of islands can generate a global recession on all islands through the endogenous information mechanism. Fourth, our model with a production economy sheds light on several puzzling empirical facts on asset price comovement. More information about idiosyncratic shocks results in individual asset prices being more responsive to idiosyncratic shocks and relatively less responsive to the aggregate shock. Hence, a lower degree of comovement of asset prices as well as a higher efficiency of resource allocation is expected to be accompanied by a higher GDP.

Finally, we extend the static model into an overlapping generations (OLG) dynamic framework, deriving several additional economic insights. The OLG model provides a dynamic equilibrium setting to study the process of saving and capital accumulation. The equilibrium is therefore dynamically linked across periods through savings. The nature of equilibrium in each period is path-dependent, depending not only on the realization of the productivity shock in the current period but also on capital accumulation over past periods. We show that our dynamic model possibly has two steady-state equilibria, meaning that the economy can exhibit self-fulfilling uncertainty traps. The transitional dynamics of our OLG model characterize a two-stage economic crisis. A medium-sized shock to the economy initially generates a mild recession along a unique equilibrium path. But as capital accumulation deteriorates the economy will eventually reach a tipping point, with multiple equilibria starting to emerge. A self-fulfilling uncertainty crisis can then suddenly throw the economy into a new “bad” equilibrium path. Output and capital fall dramatically and uncertainties spike. In contrast, a small-sized shock always generates a unique equilibrium path without the second stage.\(^2\)

\(^1\)Brunnermeier (2009) discusses various other amplification mechanisms of financial markets.
\(^2\)These implications of our OLG model are qualitatively consistent with some observed patterns of the recent financial crisis. In fact, the initial recession did not look particularly severe until the third quarter of 2008, when full financial panic broke out after the collapse of Lehman Brothers and aggregate output fell sharply. It is now widely
Prior empirical studies support our model’s key implication on information quality across business cycles. Jiang, Habib, and Gong (2015) provide evidence that management forecast errors, measured as the difference between forecasted earnings per share (EPS) and actual EPS, increase during economic recessions. Loh and Stulz (2017) document that forecast errors of financial analysts are significantly higher during recessions/crises than during good times.

Related Literature. A burgeoning literature in finance studies the informational feedback effects of financial markets (see Bond, Edmans, and Goldstein (2012) for an extensive survey of this literature). This literature argues that firm managers on the real side of the economy learn from financial prices. Among others, Goldstein, Ozdenoren, and Yuan (2013) and Sockin and Xiong (2015) develop clean model frameworks showing how prices in the secondary financial market can aggregate the dispersed information of speculators and guide firm managers or investors to make better real investment decisions. The learning in this literature is one way — the real sector learns from financial markets. On the other hand, the accounting literature emphasizes the opposite direction of learning — arguing that firm managers typically know more than financial market participants — and focuses on studying how firm managers (i.e., insiders) disclose information to the capital market, based on which financial speculators trade and security prices are formed. Our paper advances these two bodies of literature by introducing and studying mutual (two-way) learning between the real sector and financial markets, similar to Sockin (2017), Straub and Ulbricht (2017), and Wu, Miao, and Young (2017). The two-way learning mechanism sheds light on important questions, such as how a financial price is formed, where the information comes from, and how the different sources of information interact.

The finance literature pioneered by Grossman and Stiglitz (1980) and Verrecchia (1982) studies information production (or acquisition) in financial markets. Recent work by Goldstein and Yang (2015) analyzes a model where two different groups of financial traders are informed of different fundamentals of a security. They show that trading as well as information acquisition by these two groups of financial traders exhibit strategic complementarities. Ganguli and Yang (2009) study a model where traders can obtain private information about the supply of a stock in addition to that about its payoff. They show complementarity in information acquisition and the existence of multiple equilibria. Our model introduces the real sector and aggregate production into a Grossman-Stiglitz-type model; information acquisition in our model takes place both in the real sector and in financial markets. Adding to this literature, our paper shows that complementarity in information production exists between the real sector and the financial sector. Our model provides a micro-believed that a deterioration in fundamentals and a loss of confidence together drive this type of two-stage crisis (see, for example, the stamp lecture on January 13, 2009 by Fed Chairman Ben Bernanke).

foundation for the two-factor structure of the asset payoff in Goldstein and Yang (2015). Our paper also adds to the recent literature by showing that the informational interplay between the real sector and the financial sector can have important macroeconomic implications.\footnote{Goldstein and Yang (2017a) analyze a model where there are multiple dimensions of uncertainty and market prices convey information to real decision-makers. They focus on studying the effect of disclosing public information on real efficiency. They also study the information acquisition of financial speculators, but not that of the real sector.}

A large literature in macroeconomics documents robust evidence of countercyclical uncertainty — both real uncertainty and financial uncertainty increase during recessions. Real uncertainty is often proxied by firm-level dispersion in earnings, productivity and output, and the volatility of aggregate output forecast errors, while financial uncertainty is often measured by financial market volatility and the VIX index (Bloom (2009), Bloom et al. (2012), Jurado, Ludvigson, and Ng (2015)). An ongoing heated debate in this literature concerns the question of causality, i.e., whether uncertainty is a cause of or merely a response to recessions and where it comes from (see, e.g., Bachmann and Bayer (2013, 2014)). Our paper contributes to this debate by providing a theoretical framework that is able to account for the three variables — real uncertainty, financial uncertainty, and aggregate economic activities — simultaneously and show how they are related.\footnote{Benhabib, Liu, and Wang (2016b) study endogenous information acquisition of firms that links real uncertainty and economic activities. However, there is no financial market in the model there and that paper does not touch upon financial uncertainty. Veldkamp (2005) and Van Nieuwerburgh and Veldkamp (2006) study learning asymmetries in business cycles, without involving financial markets.}

Bacchetta, Tille, and Wincoop (2012) also study the self-fulfilling nature of uncertainty. In their model with an endowment economy, if agents believe that pure sunspots matter for asset prices, then the perceived risk of future prices will increase. As a result, current asset prices will indeed be affected. The uncertainty is self-fulfilling because there also exists another equilibrium in which asset prices are certain and hence bear zero risk. Fajgelbaum, Schaal and Taschereau-Dumouchel (2016) propose a theory of self-reinforcing episodes of high uncertainty and low activity, through the mechanism of the “wait-and-see” effect together with agents learning from the actions of others. In contrast to these contributions, self-fulfilling uncertainty in our model comes from the information interdependence between financial markets and the real economy. This information interplay also allows us to study the impact of uncertainties on real economic activities.

Our model is related to a small body of the macroeconomics literature that studies how financial markets affect business cycle fluctuations through information channels.\footnote{Among others, Reis (2006), Angeletos and Pavan (2007), Hellwig and Veldkamp (2009), Vives (2017), Colombo, Femminis, and Pavan (2014), and Mäkinen and Ohl (2015) study information acquisition and efficiency.} Angeletos, Lorenzoni and Pavan (2010) build a two-stage feedback model where financial markets in the second stage learn from the volume of asset selling of entrepreneurs in the first stage, which generates strategic complementarity in investment that amplifies non-fundamental shocks. Benhabib, Liu, and Wang (2016a) present a self-fulfilling business cycle model, where financial market sentiments affect the price of capital, which signals the fundamentals of the economy to the real side and consequently
leads to real output that confirms the sentiments. David, Hopenhayn, and Venkateswaran (2016) conduct a quantitative study that links imperfect information and resource misallocation, where firms learn from both internal sources and stock market prices about one dimension of fundamental uncertainty. The information is exogenous in their paper, and they conclude that firms turn primarily to internal sources for information, rather than to financial markets.\footnote{Because David, Hopenhayn, and Venkateswaran (2016) consider neither endogenous information acquisition nor the feedback on information production between the real side and financial markets, incorporating our mechanism in their quantitative study may yield new results; see our numerical calibration in Section V.} Compared with the aforementioned studies, ours shows that the amount of information in the economy is endogenous, and that there is feedback between the level of economic activity and the amount of information, amplified through the mutual learning between firms and financial markets.

Our model’s cross-sectional implication on asset pricing comovements is closely related to and motivated by the study of Peng and Xiong (2006), who show that limited investor attention leads to category-learning behavior, that is, investors tend to process more market- and sector-factor information than firm-specific information. As a consequence, return correlations between firms can be higher than their fundamental correlations, and sectors with a higher average return correlation across firms will exhibit less informative stock prices. Similarly, Veldkamp (2006) argues that investors endogenously purchasing same information results in comovement of asset prices. Unlike us, these works study pricing comovements in an exchange economy and hence they do not link pricing comovements to fluctuations in the business cycle and investment efficiency as we do.

Finally, equilibrium multiplicity due to strategic complementarity in information production in our model also adds to the large literature on coordination failures and multiple equilibria. Multiple equilibria exist in these models because each individual agent would like to do what others do. So if there is enough heterogeneity to reduce their incentives to act like others, multiple equilibria can disappear. For example, Ball and Romer (1991) show that if the fixed menu cost is heterogeneous, equilibrium multiplicity is still possible but depends crucially on the shape of the distribution function of the fixed menu cost. Morris and Shin (1998) show that heterogeneity in information can lead to a unique equilibrium in an otherwise multiple-equilibria model of currency attacks. Schaal and Taschereau-Dumouchel (2015) apply the global games approach developed by Morris and Shin (1998) to remove multiple equilibria in a model in which firms coordinate on capacity utilization. Interestingly, we find that heterogeneity across firms in productivity or the information acquisition cost can actually increase, rather than reduce, the possibility of multiple equilibria in our model. This result is in sharp contrast to the types of coordination failure in other models.

The paper is organized as follows. In Section I, we present the simple baseline model. In Section II, we extend our baseline model to study endogenous information. In Section III, we further extend the model to a macroeconomic framework. In Section IV, we extend the static model to an OLG
dynamic framework. Section V provides numerical illustrations of our model. Section VI concludes.

I. The Baseline Model

In this section, we present a simple baseline model with one firm, one financial market, and with exogenous information. The firm faces two uncertainties: a demand shock and a supply (or productivity) shock. The firm has some information about the supply shock while the financial market has some information about the demand shock. We show that there exists two-way learning between the firm and the financial market.

A. Setup

There are two types of agents: firm $j$ and a group of financial market traders (speculators). There are two types of goods: an intermediate capital good and a final good. The price of the final good is normalized as the numeraire, $P = 1$.

**Intermediate Goods Firm.** Firm $j$ is an intermediate goods firm. It produces the intermediate capital good $Y_j$ using the final good as an input according to the production function

$$Y_j = Z A_j K_j^\eta, \quad \text{for } 0 < \eta < 1,$$

where $Z$ is the common productivity shock to the whole economy (regarded as a constant in the baseline model), $A_j$ is firm $j$'s productivity, and $K_j$ is the investment input of the final good.$^8$ The input $K_j$ fully depreciates after production. We will show that firm $j$ borrows the investment input at interest rate $R_f = 1$.

The market demand function of the intermediate capital good $Y_j$ is assumed to be

$$Y_j = \left( \frac{1}{P_j} \right) \theta \epsilon_j Y,$$

where $P_j$ is the price of the capital good $j$ (in terms of the final good), and $\epsilon_j$ measures the idiosyncratic demand shock to good $j$. Moreover, in the baseline model $Y$ is an exogenous constant, which corresponds to aggregate output (real GDP) (denote $y \equiv \log Y$), whereas parameter $\theta$ measures the price elasticity of demand.

**Financial Market and Traders (Speculators).** A financial market exists, where speculators trade a financial asset (a derivative) contingent on the firm’s asset value or firm value (also its total income):

$$V_j = Y_j P_j.$$
Specifically, we assume that the payoff of the financial derivative contract takes the form

\[ v_j = \log V_j. \]

Note that the log form is for tractability.\(^9\) Denote by \( q_j \) the *market trading price* of the financial derivative contract. That is, a long position of one unit of the financial asset (derivative) incurs an initial outlay of \( q_j \) and entitles to having the risky payoff \( v_j \) later.

The utility function of speculators is assumed to be

\[ U(W^i) = -\exp(-\gamma W^i), \]

where \( W^i \) is the end-of-period wealth of speculator \( i \in [0,1] \), and \( \gamma \) is the risk-aversion (CARA) coefficient. The initial wealth of a speculator is assumed to be \( W_0 \) and the risk-free (gross) interest rate is \( R_f \equiv 1 \). This means that if a speculator takes a position of \( m \) units of the financial asset, his end-of-period wealth would be

\[ W^i = (W_0 - mq_j) R_f + mv_j = W_0 + m(v_j - q_j). \]

The assumption that speculators trade a derivative contract contingent on the firm’s asset value, \( V_j \), is made for tractability. This is along the line of the assumption in the literature that a firm’s asset value or sales revenue follows a geometric Brownian motion (see, e.g., Merton (1973) and He and Xiong (2012)). The financial derivative can also be contingent on the firm’s product price, \( P_j \) (that is, \( v_j \) takes the form \( v_j = \log P_j \)). In the latter case, the financial market can be interpreted as a *commodity financial futures market* that specializes in trading financial futures on the intermediate capital good \( Y_j \), in the spirit of Sockin and Xiong (2015). Assuming that the underlying asset of the derivative is either \( V_j \) or \( P_j \) is to ensure that the payoff of the underlying asset follows a log-normal distribution and thus to achieve tractability. This parallels the modeling device that assumes a *specific* function form of noisy trading (or asset supply) as in Goldstein, Ozdenoren, and Yuan (2013), Sockin and Xiong (2015), and Goldstein and Yang (2017a).

The net aggregate supply of the financial asset (i.e., derivative) is assumed to be 0. The demand of noise/liquidity traders in the financial market is \( n_j \), where \( n_j \) follows distribution \( n_j \sim N(0, \tau_n^{-1}) \).

**Uncertainties and Information.** The firm faces two uncertainties: productivity (or supply) shock \( A_j \) and demand shock \( \varepsilon_j \). Their prior distributions are \( \log A_j \equiv a_j \sim N(\frac{1}{2} \tau_a^{-1}, \tau_a^{-1}) \) and \( \log \varepsilon_j \equiv \varepsilon_j \sim N(-\frac{1}{2} \tau_{\varepsilon}^{-1}, \tau_{\varepsilon}^{-1}) \). And \( a_j \) and \( \varepsilon_j \) are independent. The common productivity shock \( Z \)

\(^9\)Goldstein and Yang (2017a) study the case in which the financial asset’s payoff is nonlinear with a log-normal distribution. They show numerically without analytical solutions that being more informative about one factor motivates speculators to acquire more information about the other factor; that is, our result (Lemma 1) holds true even under a log-normal distribution of the financial contract’s payoff.
is public information (denote \( z = \log Z \)).

In the baseline model, we assume that the firm and the financial market have some \textit{exogenous} (imperfect) information about \( a_j \) and \( \varepsilon_j \), respectively. Specifically, firm \( j \) possesses or is endowed with a noisy signal about its own productivity,

\[ s_j = a_j + e_j, \]

where \( e_j \sim N(0, \tau^{-1}_s) \). Firm \( j \) will disclose its signal \( s_j \) to the financial market.\(^{10}\) For simplicity, we assume that the firm has no private information about the demand shock, \( \varepsilon_j \).\(^{11}\)

In the financial market, as in Grossman and Stiglitz (1980), there is a continuum of traders with unit mass. The traders are of two types: informed and uninformed. An informed trader \( i \) has a noisy private signal

\[ x^i_j = \varepsilon_j + g^i_j, \]

where \( g^i_j \sim N(0, \tau^{-1}_x) \) and \( g^i_j \) is independent across different informed traders \( i \). An uninformed trader has no private signal regarding \( \varepsilon_j \). The proportion of informed traders is \( \lambda \), which is exogenous in the baseline model.

**Timeline.** The sequence of events (within the one period) in the baseline model is as follows:

\(- T_1: \) Firm \( j \) discloses its signal \( s_j \) to the financial market.
\( T_2: \) Financial market trading takes place, and the financial price \( q_j \) is realized.
\( T_3: \) Firm \( j \) makes its investment decision, \( K_j \), based on information \( \{s_j, q_j\} \).
\( T_4: \) The income or asset value, \( V_j \), is realized. The payoff of the financial contract is delivered.

The above timeline captures two-way information learning and production in a simple way.

**B. Equilibrium**

The equilibrium consists of a financial market equilibrium at \( T_2 \) and the firm’s investment decision at \( T_3 \). We conduct analysis by backward induction.

**Firm \( j \)’s Investment Decision at \( T_3 \).** Firm \( j \) maximizes its \textit{expected} profit,

\[ K_j \equiv K(s_j, q_j) = \arg \max_{K_j} \mathbb{E} \left[ P_j Y_j - R_j K_j | s_j, q_j \right], \tag{4} \]

subject to constraints (1) and (2). Here, \( \mathbb{E}(\cdot | s_j, q_j) \) is the conditional expectation operator over \( a_j \) and \( \varepsilon_j \). It is well understood that a firm’s objective is not always well defined in an asymmetric-

\(^{10}\) As will become clear later, a firm has incentives to disclose its information to the financial market because the disclosure can “attract” more information from the financial market, which can guide the firm to make better investment decisions. Goldstein and Yang (2017a) show that firms always have incentives to disclose their information orthogonal to traders (see also Bond and Goldstein (2015)).

\(^{11}\) We will relax this assumption in Section II.C to allow the firm to have information on the demand shock as well.
information environment. For simplicity and convenience, we assume that firms maximize their expected profit. Alternatively, we can assume that firms are run by risk-neutral entrepreneurs.

Financial Market Trading at $T_2$. In the financial market, the information set of informed speculators is $\{s_j, q_j, x^j\}$ while that of uninformed speculators is $\{s_j, q_j\}$. An informed speculator chooses his risky asset holdings, $m^{Ii}$, to maximize his utility,

$$m^{Ii}(s_j, q_j, x^j) = \arg \max_{m^{Ii}} \mathbb{E}[U(W^{Ii})|s_j, q_j, x^j],$$  \hspace{1cm} (5)

where $W^{Ii} = (W_0 - c) + m^{Ii}(v_j - q_j)$ and $c$ denotes a constant expense, to be explained later. An uninformed speculator chooses his risky asset holdings, $m^{Ui}$, to maximize his utility,

$$m^{Ui}(s_j, q_j) = \arg \max_{m^{Ui}} \mathbb{E}[U(W^{Ui})|s_j, q_j],$$  \hspace{1cm} (6)

where $W^{Ui} = W_0 + m^{Ui}(v_j - q_j)$. In (5) and (6), $\mathbb{E}(\cdot)$ is the expectation operator over $v_j$.

**Definition 1** An equilibrium consists of the financial price function $q_j = q(s_j, \varepsilon_j, n_j)$ and the firm’s investment decision function $K_j = K(s_j, q_j)$, such that

i) the price $q(s_j, \varepsilon_j, n_j)$ clears the financial market at $T_2$,

$$\lambda \int_0^1 m^{Ii} di + (1 - \lambda) \int_0^1 m^{Ui} di + n_j = 0,$$  \hspace{1cm} (7)

where, for given $K_j = K(s_j, q_j)$, $m^{Ii}$ and $m^{Ui}$ solve (5) and (6), respectively;

ii) given price $q(s_j, \varepsilon_j, n_j)$, investment decision $K(s_j, q_j)$ solves the firm’s problem (4).

C. Characterization of Equilibrium

First, we characterize the financial market equilibrium. We conjecture that $\log K_j \equiv k_j = k(s_j, q_j)$ is a linear function in Definition 1. We also conjecture a linear price function,

$$q_j = \beta_0 + \beta_1 \varepsilon_j + \beta_2 s_j + \beta_3 n_j,$$  \hspace{1cm} (8)

where $\beta_0$, $\beta_1$, $\beta_2$, and $\beta_3$ are coefficients. When combined with $s_j$, the price $q_j$ can be converted into another piece of public information about $\varepsilon_j$,

$$\tilde{q}_j(q_j, s_j) = \frac{q_j - \beta_0 - \beta_1 \varepsilon_j - \beta_2 s_j}{\beta_1} = \varepsilon_j + \beta_3 n_j \equiv \varepsilon_j + \theta^q_j,$$  \hspace{1cm} (9)

where $\theta^q_j \sim N(0, \tau_q^{-1})$ with $\tau_q^{-1} = \beta_3^2 \tau_n^{-1}$. Information set $\{s_j, q_j\}$ is a one-to-one mapping to $\{s_j, \tilde{q}_j\}$. We have Lemma 1.

**Lemma 1** In the equilibrium of the financial market, for a given $\lambda$, $\tau_q$ is an increasing function
Lemma 1 states that when the precision of the firm’s disclosed information about \( a_j \) increases, the informativeness of the financial price about \( \varepsilon_j \) also increases. The intuition is as follows. The total uncertainty over \( v_j \) is the sum of the uncertainties over \( a_j \) and \( \varepsilon_j \). When uncertainty over \( a_j \) decreases under a higher precision \( \tau_s \), informed traders have incentives to trade more aggressively, which overwhelms the trading of noise/liquidity traders, thus increasing the informativeness of the financial price.

Lemma 1 shows that the financial price comes partially from information disclosure in the real sector and partially from price discovery in the financial market. These two sources of information interact.

Next, we move to characterize firm \( j \)’s investment decision at \( T_3 \). The first-order condition (FOC) of (4) implies

\[
k_j = k(s_j, \hat{q}_j) = \phi'_0 + \Theta (1 - \frac{1}{\theta}) \frac{\tau_s}{\tau_s + \tau} s_j + \frac{\Theta}{\tau} \frac{\tau_q}{\tau + \tau_q} \hat{q}_j,
\]

where \( \Theta = -\frac{1}{\eta(1 - \frac{1}{\theta}) - 1} \in (1, \theta) \) and the constant coefficient \( \phi'_0 \) is provided in Appendix B. Because \( \hat{q}_j \) is a linear function of \( s_j \) and \( q_j \) by (9), (10) implies that \( k_j \) is also a linear function of \( s_j \) and \( q_j \).

**Lemma 2** The firm’s investment decision at \( T_3, K(s_j, q_j) \), is given by (10) (together with (9)).

The realized profit of firm \( j \) at \( T_4 \) is \( \pi(a_j, \varepsilon_j, s_j, \hat{q}_j) = P_j(\varepsilon_j, Y_j) Y_j(a_j, K_j) - K_j(s_j, q_j). \) Hence, the expected profit perceived at the stage of investment at \( T_3 \) is \( \mathbb{E}[\pi(a_j, \varepsilon_j, s_j, \hat{q}_j)|s_j, \hat{q}_j]. \) Exploiting the law of iterated expectations, we find the ex ante expected profit of firm \( j \) perceived at \( T_0 \):

\[
\Pi(\tau_s, \tau_q; Y, Z) = \mathbb{E}[\pi(a_j, \varepsilon_j, s_j, \hat{q}_j)|s_j, \hat{q}_j]
= \left[ 1 - \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta - 1} \cdot \left( Y^\frac{1}{\theta} Z^{1 - \frac{1}{\theta}} \right)^\Theta \mathbb{E} \left( \mathbb{E} \left( A_j^{1 - \theta} \psi_j^\frac{1}{\theta} | s_j, \hat{q}_j \right) \right) \cdot \mathbb{E} \left( A_j^{1 - \theta} \psi_j^\frac{1}{\theta} | s_j, \hat{q}_j \right),
\]

where

\[
\mathbb{E} \left( A_j^{1 - \theta} \psi_j^\frac{1}{\theta} | s_j, \hat{q}_j \right) = \exp \left\{ \frac{1}{2} \left[ \left( \Theta (1 - \frac{1}{\theta}) \right)^2 - \Theta (1 - \frac{1}{\theta}) \right] \frac{1}{\tau_a} + \frac{1}{2} \left[ \left( \Theta \frac{1}{\theta} \right)^2 - \Theta \frac{1}{\theta} \right] \frac{1}{\tau_e} \right\},
\]

by noting that the outer \( \mathbb{E}(\cdot) \) is the unconditional expectation operator over \( s_j \) and \( \hat{q}_j \).

It is easy to show that

\[
\frac{\partial \Pi}{\partial \tau_s} > 0 \quad \text{and} \quad \frac{\partial \Pi}{\partial \tau_q} > 0.
\]

The intuition behind the above comparative statics is easy to understand. When the firm has a
more precise signal about \( a_j \) or \( \varepsilon_j \), it makes a better investment decision because its investment can be more closely aligned with the realized productivity or demand shock. Moreover,

\[
\frac{\partial^2 \Pi}{\partial \tau_s \partial \tau_q} > 0, \tag{13}
\]

which means that the precisions of signals \( a_j \) and \( \varepsilon_j \) are complementary in affecting the firm’s ex ante profit. In other words, the information value of knowing about one shock increases with the information precision of the other shock. The intuition is as follows. When \( \tau_q \) is higher, the firm has more accurate information about its demand. This enables the firm to make a better investment decision that is more closely aligned with the true demand shock and increases its profit multiplicatively for every realized productivity shock. Therefore, the incremental profit of knowing the realization of the productivity shock (versus not) is also higher for a higher \( \tau_q \). This means that the firm has a higher stake to acquire information about \( a_j \) when \( \tau_q \) is higher. Similarly,

\[
\frac{\partial^2 \Pi}{\partial \tau_s \partial Y} > 0 \quad \text{and} \quad \frac{\partial^2 \Pi}{\partial \tau_s \partial Z} > 0.
\]

A key insight of the baseline model is that the learning between the financial market and the real economy occurs both ways. The financial market learns information from a firm’s disclosure in trading, and conversely, the firm learns information from the financial price in making its real (investment) decision.

II. The Model with Endogenous Information

In this section, we extend the baseline model to allow for endogenous information acquisition. The purpose is to shed light on the information acquisition of the firm and that of the financial market, and show how they interact.

A. Setup

We add \( T_0 \) to the timeline. At \( T_0 \), after the common productivity shock \( Z \) is realized (which becomes public information), the firm and the financial market simultaneously make their information acquisition decisions.

By paying an information acquisition cost \( b > 0 \) (in terms of the final good), the firm receives a signal \( s_j = a_j + e_j \), where \( e_j \sim N(0, \tau_s^{-1}) \); otherwise, it receives a less precise signal \( s_j = a_j + e_j \), where \( e_j \sim N(0, \bar{\tau}_s^{-1}) \) and \( \bar{\tau}_s > \tau_s \). Note that \( \tau_s = 0 \) corresponds to the extreme case in which the firm receives a useless signal. In short, \( \tau_s \in \{\tau_s, \bar{\tau}_s\} \). In addition, in the spirit of the classic moral hazard problem (concerning hidden actions), we assume that a firm’s choice of information precision \( \tau_s \) is private information (i.e., unobservable to outsiders, including financial market participants). In other words, the firm’s choice of information precision has no strategic effect on financial market
participants.

In the financial market, a trader can choose to be informed or uninformed. By paying an information acquisition cost \( c > 0 \) (in terms of the final good), a trader receives a private signal \( x^i_j = \varepsilon_j + \theta^i_j \) with \( \theta^i_j \sim N(0, \tau^{-1}_x) \), as specified in the baseline model; otherwise, it receives no signal (or equivalently a useless signal). The proportion of informed speculators, \( \lambda \), is endogenous.

Our assumption that the firm and financial markets have *comparative advantages* in acquiring information about different types of uncertainties is realistic. On the one hand, the firm has an advantage over outsiders, including financial analysts, in obtaining information about its own productivity shock. On the other hand, financial analysts in major investment banks specializing in different regional or sectoral submarkets could, in aggregate, be better informed about the demand for the firm’s product than the firm itself. Furthermore, in Section II.C, we will relax the assumption to allow the firm to obtain information on the demand shock as well.

**B. Equilibrium**

*Information Acquisition Decision of Speculators.* The proportion \( \lambda \) is determined such that an uninformed speculator and an informed speculator have the same expected utility:

\[
\frac{EV(W^{i})}{EV(W^{U})} = 1, \tag{14}
\]

where \( EV(W^i) \equiv \mathbb{E}[U(W^i)|s_j,q_j] \). We have the following result.

**Proposition 1** In the equilibrium of the financial market with endogenous \( \lambda \), \( \tau_q \) is a function of \( \tau_s \) and \( c \), written as \( \tau_q = \tau_q(\tau_s; c) \). We have the comparative statics \( \frac{\partial \tau_q}{\partial \tau_s} > 0 \) and \( \frac{\partial \tau_q}{\partial c} < 0 \).

Proposition 1 states that with taking the endogenous \( \lambda \) into account, the informativeness of the financial price about \( \varepsilon_j \) increases as the precision of the firm’s information about \( a_j \) increases. The intuition behind the comparative statics is as follows. There are two driving forces under the comparative statics \( \frac{\partial \tau_q}{\partial \tau_s} > 0 \). First, as in the earlier discussion of Lemma 1, when uncertainty over \( a_j \) decreases, informed traders trade more aggressively, increasing the informativeness of the financial price. Second, in the spirit of Grossman and Stiglitz (1980), (14) implies \( e^\gamma c = \sqrt{\frac{\text{Var}[\varepsilon_j|s_j,q_j]}{\text{Var}[\varepsilon_j|s_j,q_j,x^i_j]}} \), that is,

\[
e^\gamma c = \sqrt{\frac{\text{Var}[(1 - \frac{1}{b}) a_j|s_j] + \text{Var}[(\frac{1}{b}) \varepsilon_j|s_j,q_j]}{\text{Var}[(1 - \frac{1}{b}) a_j|s_j] + \text{Var}[(\frac{1}{b}) \varepsilon_j|s_j,q_j,x^i_j]}}. \tag{15}
\]

the right-hand side (RHS) of which is the gain in information advantage for an informed speculator over an uninformed one. When one dimension of uncertainty (the term \( \text{Var}[(1 - \frac{1}{b}) a_j|s_j] \)) is reduced, the information advantage on the other dimension of uncertainty (the term \( \text{Var}[(\frac{1}{b}) \varepsilon_j|\cdot]\)) becomes more valuable. For example, in the extreme case when \( \text{Var}[(1 - \frac{1}{b}) a_j|s_j] \) is very large,
being informed has little advantage over being uninformed. Hence, when the precision of signal $s_j$ increases and thus $Var(a_j|s_j)$ decreases, an uninformed speculator has incentives to switch to being informed by paying a cost $c$. When more speculators acquire information, price informativeness also improves.\footnote{Of course, there is a third force, namely, the classic free-rider problem in Grossman and Stiglitz (1980). A more informative price reduces the incentive for a trader to acquire information.} As for the comparative statics $\frac{\partial \tau_q}{\partial c} < 0$, a lower $c$ induces more traders to become informed, causing price informativeness to improve.

**Information Acquisition Decision of the Firm.** Considering that profit function $\Pi(\tau_s, \tau_q; Y, Z)$ given in (11) has the properties $\frac{\partial \Pi}{\partial \sigma_s} > 0$ and $\frac{\partial^2 \Pi}{\partial \tau_q \partial \sigma_s} > 0$ shown in (12) and (13), we can obtain firm $j$’s optimal information acquisition decision at $T_0$:

$$\tau_s = \begin{cases} \hat{\tau}_s & \text{if } \tau_q \geq \hat{\tau}_q(Y, Z, b) \\ \underline{\tau}_s & \text{otherwise} \end{cases}$$

(16)

where threshold $\hat{\tau}_q \equiv \hat{\tau}_q(Y, Z, b)$ is defined as the unique root to the equation

$$\Pi(\tau_s = \bar{\tau}_s; \hat{\tau}_q, Y, Z) - \Pi(\tau_s = \underline{\tau}_s; \hat{\tau}_q, Y, Z) = b.$$  

(17)

It is easy to show that $\frac{\partial s_q(Y, Z, b)}{\partial Y} < 0$, $\frac{\partial s_q(Y, Z, b)}{\partial Z} < 0$, and $\frac{\partial s_q(Y, Z, b)}{\partial b} > 0$. In other words, the firm’s information acquisition decision given by (16) is a step function, written as $\tau_s(\tau_q; Y, Z, b)$.

**Proposition 2** The optimal information acquisition decision of the firm at $T_0$, $\tau_s(\tau_q; Y, Z, b)$, is given by (16). We have that $\frac{\partial \tau_s}{\partial \tau_q} \geq 0$, $\frac{\partial \tau_s}{\partial Y} \geq 0$, $\frac{\partial \tau_s}{\partial Z} \geq 0$, and $\frac{\partial \tau_s}{\partial b} \leq 0$.

Proposition 2 states that if and only if the firm expects the financial efficiency $\tau_q$ to exceed the threshold value $\hat{\tau}_q(Y, Z, b)$ would it choose a high precision $\tau_s = \bar{\tau}_s$. This is because precisions of signals $a_j$ and $\varepsilon_j$ are complementary in affecting the firm’s ex ante profit. Intuitively, when the uncertainty over $\varepsilon_j$ is reduced, information about $a_j$ becomes more valuable in maximizing the firm’s expected profit. The equilibrium $\tau_s$ also depends on $Y$ and $Z$; that is, when $Y$ or $Z$ is higher, the marginal benefit of increasing the signal precision $\tau_s$ is also higher, and so the firm is more likely to acquire information about $a_j$.

Proposition 2 is a novel result of our model. Earlier work in the literature such as Goldstein and Yang (2015) has shown information production complementarity within the financial market. Our paper shows information production complementarity between the real side of the economy and the financial side.

**Full Equilibrium.** Proposition 1 gives the reaction function $\tau_q(\tau_s; c)$ while Proposition 2 gives the reaction function $\tau_s(\tau_q; Y, Z, b)$. Let

$$\tau^*_q \equiv \tau_q(\tau_s = \underline{\tau}_s; c)$$
and
\[ \tau_{qs}^{**} \equiv \tau_q(\tau_s = \bar{\tau}_s; c). \]

Clearly, \( \tau_{qs}^{**} > \tau_{qs}^* \) by Proposition 1. Proposition 3 follows.

**Proposition 3** The rational expectations equilibrium, characterized by the pair \((\tau_s, \tau_q)\) for given \((Y, Z, b, c)\), solves the system of equations \(\tau_q(\tau_s; c)\) (given in Proposition 1) and \(\tau_s(\tau_q; Y, Z, b)\) (given in Proposition 2). There are three possible equilibrium cases:

i) Case 1: \(\bar{\tau}_q > \tau_{qs}^{**}\). The equilibrium is unique: \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{qs}^*)\).

ii) Case 2: \(\bar{\tau}_q \in [\tau_{qs}^*, \tau_{qs}^{**}]\). There are multiple (two) equilibria: \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{qs}^*)\) or \((\bar{\tau}_s, \tau_{qs}^{**})\).

iii) Case 3: \(\bar{\tau}_q < \tau_{qs}^*\). The equilibrium is unique: \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{qs}^{**})\).

The threshold \(\tau_q = \bar{\tau}_q(Y, Z, b)\) is given by (17).

The intuition behind Proposition 3 is as follows. The two-way feedback in information production between the financial sector and the real sector can generate a unique equilibrium or multiple equilibria, depending on parameters \(Y, Z, b,\) and \(c\). For illustration, let us change \(Y\) while keeping \(Z, b,\) and \(c\) constant. Recall that when aggregate output \(Y\) is sufficiently low (high), the firm’s incentive to acquire information is already weak (strong) enough. Specifically, if \(Y\) is so low (and hence threshold \(\bar{\tau}_q(Y, Z, b)\) is so high) such that not acquiring information is a dominant strategy for the firm (regardless of whether financial price informativeness \(\tau_q = \tau_{qs}^*\) or \(\tau_{qs}^{**}\)), then a unique equilibrium exists in which the real side does not acquire information and financial efficiency is also at a lower level. This is Case 1. Conversely, if aggregate output \(Y\) is so high (and hence threshold \(\bar{\tau}_q(Y, Z, b)\) is so low) such that acquiring information is a dominant strategy for the firm, then a unique equilibrium exists in which the real side acquires information and financial efficiency is also at a higher level. This is Case 3. Between these two extreme cases, there are multiple self-fulfilling equilibria, which is Case 2.

Figure 1 (with three panels) illustrates the three equilibrium cases, corresponding to different levels of aggregate output (i.e., \(Y_L < Y_M < Y_H\)). The two curves in each panel are the two reaction functions (i.e., \(\tau_q(\tau_s; c)\) and \(\tau_s(\tau_q; Y, Z, b)\)), and their intersection(s) represent the equilibrium.\(^{13}\) It is easy to see that when \(Y\) is kept constant, a change in \(b\) or \(c\) or \(Z\) (where a change in \(c\) corresponds to a horizontal shift of curve \(\tau_q(\tau_s; c)\) in Figure 1) also leads to different equilibrium cases.

\(^{13}\)Typically, \(\tau_q(\tau_s; c)\) is a curve and not a straight line. But when \(\tau_x = +\infty\), it is a straight line.
Figure 1. Three equilibrium cases, with $Y_L < Y_M < Y_H$. Case 1: top; Case 2: middle; Case 3: bottom.

C. Discussion

Here we discuss two simplified assumptions of our model. First, for tractability and to obtain closed-form solutions, we have assumed the binary choice of information acquisition of the firm. We can instead assume that the firm’s information acquisition is a continuous choice, and our model
results would not change qualitatively. In fact, in this case, the reaction curve \( \tau_s(\tau_g;Y,Z,b) \) in Figure 1 is “smoothed” and becomes an “S”-shaped curve, so the nature of the equilibrium (i.e., the number of intersections between the two reaction curves) is the same as in Figure 1. Second, for simplicity, in Section I we have assumed that the firm has no private information about the demand shock \( \varepsilon_j \). We can relax this assumption, and our model results are robust. To save space here, we provide the details in our NBER working paper version of Benhabib, Liu, and Wang (2018).

III. The Macroeconomic Model

In this section, we extend the model to a macroeconomic framework. The extended model provides macroeconomic background for the baseline model and endogenizes various exogenous specifications and variables of the baseline model. In particular, aggregate output (i.e., real GDP), \( Y \), is endogenized, which yields a number of novel implications.

A. Setup

Final Goods Firms. The final (consumption) good is produced with a continuum of capital goods as inputs according to a Dixit-Stiglitz production function

\[
Y = \left[ \int e_j^\frac{1}{\theta} Y_j^{\theta-1} d\varepsilon_j \right]^{\frac{1}{\theta-1}},
\]

where \( j \in [0,1], \theta > 1 \) is the elasticity of substitution between intermediate capital goods, and \( \varepsilon_j \) measures the demand shock to intermediate good \( j \).

The representative competitive final goods firm maximizes profits,

\[
\max P \left[ \int e_j^\frac{1}{\theta} Y_j^{\theta-1} d\varepsilon_j \right]^{\frac{1}{\theta-1}} - \int P_j Y_j d\varepsilon_j,
\]

where \( P_j \) is the price of intermediate good \( j \). The price of the final good, \( P \), is normalized as the numeraire price, i.e., \( P \equiv 1 \). The first-order condition of (19) with respect to \( Y_j \) gives the demand schedule for good \( j \),

\[
Y_j = \left( \frac{1}{P_j} \right)^\theta \varepsilon_j Y,
\]

which endogenizes the demand function of (2).

Intermediate Goods Firms. There is a continuum of intermediate (capital) goods firms with unit measure, indexed by \( j \). The setup for a typical firm, firm \( j \), is presented in Section I.A. We can think of each intermediate good as being produced by one firm that is located on one island in the spirit of Lucas (1972). Both \( a_j \) and \( \varepsilon_j \) are i.i.d. across firms (or islands).

Financial Markets. In the financial market(s), there is a continuum of financial assets. Financial asset (derivative) \( j \) is contingent on intermediate goods firm \( j \)’s asset value, \( V_j = Y_j P_j \). The
payoff of financial derivative contract $j$ is $v_j = \log V_j$. The demand from noise/liquidity traders for financial asset $j$ is $n_j \sim N(0, \tau_n^{-1})$, and $n_j$ is independent across financial assets. It might be the case that each island has one financial market with financial asset $j$ being traded in the financial market on island $j$, or the case that there is only one financial market (exchange) where all the financial assets are traded. In the current framework of the aggregate economy, we can interpret noise trading as: 1) foreign capital flow, or 2) liquidity trading by some investors who must trade (for exogenous reasons such as balancing portfolios, endowment shocks, and so on).\(^{14}\)

The setup for information acquisition for a firm and on a financial asset is the same as that in Section II.

**Investors.** The economy consists of a continuum of $[0, 1] \times [0, 1]$ investors. Each investor is endowed with $W_0$ units of the final good at $T_0$.\(^{15}\) Each investor has three identities: capital supplier (i.e., lender), firm owner (i.e., shareholder), and financial market trader. The economy is decentralized, analogous to the Robinson Crusoe economy. The decisions of an investor made under different identities are independent.

We assume that $W_0$ is sufficiently high and a storage technology exists, so that in equilibrium $R_f = 1$.\(^{16}\) An investor maximizes utility

$$U(C^i) = -\exp(-\gamma C^i)$$

subject to constraint

$$C^i = W_0 + (\Pi - \chi) + D^i,$$

where $C^i$ is investor $i$’s end-of-period wealth at $T_4$. The term $\Pi$ is the aggregate profit of firms; that is, $\Pi = \int (P_j Y_j - R_f K_j) \, dj$, which corresponds to (11) by the law of large numbers. The term $\Pi - \chi$ is the aggregate net profit of the firms distributed to an investor (as an owner of firms), where $\chi \in \{0, b\}$ is the aggregate information acquisition cost to the firms.\(^{17}\) The term $D^i$ is investor $i$’s payoff in financial market trading. If he is an informed trader in financial market $j$, then $D^i = -c + m^{Hi}(v_j - q_j)$; if he is an uninformed trader, then $D^i = m^{Ui}(v_j - q_j)$. Notice that for simplicity and expositional clarity, we have assumed here that an investor can trade only in one financial market (asset). In Section III.D.2, we will provide a robustness analysis and show that our model insight holds if investors are allowed to access all financial assets and hold a portfolio.

It is easy to show that the trading (asset holding) and information acquisition decision of an

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\(^{14}\)David, Hopenhayn, and Venkateswaran (2016) also use the general equilibrium framework with noise traders.

\(^{15}\)Clearly now, by calling the “final” good, we mean not only the good produced with the intermediate inputs under Dixit-Stiglitz aggregation but also the endowment which can be used for either consumption or capital. The point is that the endowment good and the good produced under Dixit-Stiglitz aggregation are the same good.

\(^{16}\)More specifically, $W_0$ is greater than the aggregate investment given in (24) below.

\(^{17}\)We will consider the symmetric equilibrium in which either all firms or no firm acquires information.
investor (as a financial market trader) is exactly the same as that in Sections I and II.

B. Equilibrium

Within each island, the equilibrium is given by Propositions 1 to 3. Now we study the equilibrium of the aggregate economy, endogenizing $Y$. We consider the symmetric equilibrium, in which all intermediate goods firms have the same level of information precision.

To find the symmetric equilibrium, we proceed in two steps. First, suppose that the equilibrium information precision on the representative island (or equivalently, all islands $j \neq j$) is given by $(\tau_s, \tau_q)$, and work out the aggregate output $Y$. Second, given this $Y$, characterize the partial equilibrium on island $j$ as studied in Section II.B.

We take the first step and find that aggregate output is given by

$$Y = ZAK^\eta,$$  \hspace{1cm} (22)

where $A = A(\tau_s, \tau_q)$ is the endogenous aggregate TFP and $K = K(\tau_s, \tau_q; Z)$ is the aggregate investment in the economy, with

$$A = A(\tau_s, \tau_q) = \left\{ \mathbb{E} \left[ \left( \mathbb{E} \left[ \left. \left( \epsilon_j^{\frac{1}{\varphi}} A_j^{1-\frac{1}{\varphi}} | s_j, \tilde{q}_j \right) \right]^\Theta \right) \right] \right\}^{\frac{1}{\sigma - 1 - \eta}}, \hspace{1cm} (23)$$

and

$$K = K(\tau_s, \tau_q; Z) = \left[ \eta \left( 1 - \frac{1}{\vartheta} \right) Z \cdot A(\tau_s, \tau_q) \right]^{\frac{\varphi}{1 - \eta \varphi}}, \hspace{1cm} (24)$$

and the term $\mathbb{E} \left[ \left( \mathbb{E} \left[ \left. \left( \epsilon_j^{\frac{1}{\varphi}} A_j^{1-\frac{1}{\varphi}} | s_j, \tilde{q}_j \right) \right]^\Theta \right) \right]$ is calculated in (11). Aggregate output can also be expressed as

$$Y = Y(A; Z) = \left[ \eta \left( 1 - \frac{1}{\vartheta} \right) \right]^{\frac{\varphi}{1 - \eta \varphi}} \left[ Z \cdot A(\tau_s, \tau_q) \right]^{\frac{\varphi}{1 - \eta \varphi}}. \hspace{1cm} (25)$$

Equation (22) implies that despite heterogeneity among firms caused by idiosyncratic productivity shocks and demand shocks, our economy works as if there existed a representative firm with productivity $A$ and aggregate investment $K$. Proposition 4 follows.

**Proposition 4** Both the endogenous aggregate TFP, $A$, and aggregate investment, $K$, are increasing in $\tau_s$ and $\tau_q$ (given by (23) and (24), respectively). Hence, aggregate output $Y$ is increasing in $\tau_s$ and $\tau_q$ (given by (22)).

Proposition 4 highlights two effects of information frictions. First, given $K$, the endogenous aggregate TFP, $A$, measuring the efficiency of resource allocation, has the properties $\frac{\partial A}{\partial \tau_s} > 0$ and $\frac{\partial A}{\partial \tau_q} > 0$. Efficient allocation requires more resources to be allocated to firms with higher realized
$A_j$ and $\epsilon_j$. In other words, efficient investment $K_j$ should be more aligned with realized $A_j$ and $\epsilon_j$. So, more precise information about $A_j$ and $\epsilon_j$ achieved through information acquisition helps improve allocative efficiency. Second, higher uncertainty also leads to a lower level of aggregate investment, that is, $\frac{\partial K}{\partial s} > 0$ and $\frac{\partial K}{\partial q} > 0$.

Next, we take the second step. That is, given $Y$ derived in the first step, characterize the partial equilibrium on island $j$. Denote by $\tau_j$ the equilibrium on island $j$. By the partial equilibrium result shown in Section II.B, we have $\tau_j = \tau_j(\tau_j; Y, Z, b)$ and $\tau_q = \tau_q(\tau_j; c)$, where $Y = Y(\tau_j, \tau_q, Z)$ is given by (22).

By the symmetric equilibrium, we have $(\tau_s, \tau_q) = (\tau_j, \tau_q)$. Thus, the full equilibrium of the aggregate economy is given by the following joint equations

\begin{align*}
\tau_s &= \tau_s(\tau_j; Y, Z, b) \quad \text{(a firm’s optimal information choice)} \quad (26) \\
\tau_q &= \tau_q(\tau_s; c) \quad \text{(financial market equilibrium)} \quad (27) \\
Y &= Y(\tau_s, \tau_q, Z) = Z \cdot A(\tau_s, \tau_q) [K(\tau_s, \tau_q; Z)]^n, \quad \text{(aggregate economy equilibrium)} \quad (28)
\end{align*}

where (26), (27), and (28) are given by Proposition 2, Proposition 1, and Proposition 4, respectively.

**Proposition 5** The general equilibrium of the aggregate economy, characterized by triplet $(\tau_s, \tau_q, Y)$, solves the system of equations (26) to (28) for given $(b, c, Z)$. The general equilibrium has three cases:

i) when $Z < \bar{Z}$, the equilibrium is unique: $(\tau_s, \tau_q, Y) = (\tau_s, \tau_q, Y(\tau_s, \tau_q, Z))$;

ii) when $Z \leq \bar{Z}$, there are multiple (two) equilibria: $(\tau_s, \tau_q, Y) = (\tau_s, \tau_q, Y(\tau_s, \tau_q, Z))$ or $(\tilde{\tau}_s, \tilde{\tau}_q, Y(\tilde{\tau}_s, \tilde{\tau}_q, Z))$;

iii) when $Z > \bar{Z}$, the equilibrium is unique: $(\tau_s, \tau_q, Y) = (\tau_s, \tau_q, Y(\tilde{\tau}_s, \tilde{\tau}_q, Z))$.

The threshold $Z = \bar{Z}(b, c)$ is the unique root to the equation

$$\Pi(\tau_s = \tilde{\tau}_s; \tau_q^*, Y(A, Z) , Z) = b$$

and threshold $\tilde{Z} = \bar{Z}(b, c)$ is the unique root to the equation

$$\Pi(\tau_s = \tilde{\tau}_s; \tau_q^*, Y(A, \bar{Z}) , \bar{Z}) = b,$$

where $A = A(\tilde{\tau}_s, \tilde{\tau}_q^*)$, $\bar{A} = A(\bar{\tau}_s, \tau_q^*)$, and $Y(A, Z)$ is defined in (25).

The intuition behind equilibrium multiplicity in Proposition 5 is very similar to that behind equilibrium multiplicity in Proposition 3 — the root cause is strategic complementarity in information production. In the partial equilibrium, strategic complementarity in information production
exists within an island (between the financial sector and the real sector), which can generate multiple equilibria. In the full equilibrium, strategic complementarity in information production exists both within an island and between islands, and hence multiple equilibria become even more likely. In Proposition 3, the threshold for the existence of multiple equilibrium depends on \( Y \) or \( Z \) (or, more precisely, on \( Y^{\frac{b}{2}} Z^{1-b} \) seen in (11) and (17)). The only difference now is that \( Y \) itself is endogenous and is a function of \( \tau_s, \tau_q \) and \( Z \). Hence, the endogenous \( Y \) adds a further reinforcing channel, with the result that the general equilibrium becomes more sensitive to the change in \( Z \) than the partial equilibrium and multiple equilibria become more likely.\(^{18}\)

![Figure 2. Aggregate output \( Y \) in general equilibrium.](image)

To illustrate Proposition 5, Figure 2 depicts \( Y \) as a function of \( Z \) with \( c \) and \( b \) fixed (recall equation (25)). In Figure 2, when \( Z \) is low enough such that \( Z \in (-\infty, Z) \), there is a unique “bad” equilibrium; when \( Z \) is high enough such that \( Z \in (Z, +\infty) \), there is a unique “good” equilibrium. When \( Z \in [Z, Z] \), there are two self-fulfilling equilibria. Similarly, when \( Z \) is kept constant, a change in \( b \) or \( c \) also leads to different cases of equilibrium (where a change in \( b \) or \( c \) shifts the thresholds \( Z \) and \( Z \) in Figure 2).

C. Implications

We discuss four key implications of the general equilibrium given in Proposition 5.

C.1. (Implication 1) Amplification Effects

A small adverse shock (i.e., a small increase in \( c \) or \( b \), or a small decrease in \( Z \)) can have a large impact on the aggregate economy (aggregate output \( Y \)) due to the compound feedback loops of information amplification. For illustration, Figure 3 depicts the amplification effects when an adverse shock to \( c \) hits the economy (while \( b \) and \( Z \) stay the same), where each arrow represents an

\(^{18}\)We also show that the results of Proposition 5 do not change qualitatively under the setup of continuous information acquisition of firms. Details are provided in our NBER working paper of Benhabib, Liu, and Wang (2018).
economic force given in equations (26) to (28). Detailed numerical illustrations of the comparative statics with respect to $c$, $b$, and $Z$ will be provided in Section V. Our information channel of amplification contrasts with the financing channel in Kiyotaki and Moore (1997) and Jermann and Quadrini (2012), where an adverse shock originating in either the real sector or the financial sector can also lead to a large drop in aggregate output.

In particular, the amplification in our model can arise from the presence of multiple equilibria (i.e., discontinuity). That is, a small aggregate shock or pure self-fulfilling beliefs in the absence of any aggregate shock can trigger the equilibrium to switch from one regime to the other, generating a very large drop in aggregate output and investment. As illustrated in Figure 2, a small change in $Z$ around $Z = \bar{Z}$ (i.e., a slight decrease in $Z$ from above $\bar{Z}$ to below $\bar{Z}$) can trigger the equilibrium to switch from “good” to “bad”, resulting in a large drop in $Y$. This implies that a positive shock and a negative shock to $Z$ potentially have asymmetric effects on equilibrium output. Suppose that initially $Z$ is (slightly) above $\bar{Z}$. When $Z$ increases, equilibrium output increases steadily. However, when $Z$ declines, equilibrium output may exhibit a sudden large decline if the economy falls to the bad equilibrium. This also implies that a small shock and a big shock to $Z$ can have dramatically different implications: while a small decline in $Z$ leads to a steady decrease in output, a big decline in $Z$ may trigger a self-fulfilling crisis. Conducting comparative statics with respect to $c$ and $b$ instead of $Z$ yields similar patterns (see Section V).

![Figure 3. Information amplification.](image)

**C.2. (Implication 2) Real Uncertainty and Financial Uncertainty**

Our model endogenizes together the three variables — financial uncertainty, real uncertainty, and aggregate economic activity — and shows how they are related. The residual financial uncer-
tainty (or equivalently, financial market efficiency as defined in Brunnermeier (2005) and Goldstein and Yang (2015)) is given by\(^{19}\)

\[
SD(\varepsilon_j|s_j, q_j) = \sqrt{\frac{1}{\tau_\varepsilon + \tau_q}},
\]

and the residual real uncertainty (or forecast error) faced by a firm is given by

\[
SD(a_j|s_j) = \sqrt{\frac{1}{\tau_a + \tau_s}}.
\]

We have shown that an adverse shock in \(c\) or \(b\) or \(Z\) leads to a decrease in \(\tau_s\) and \(\tau_q\) together with a decrease in \(Y\), which means that a rise in both real uncertainty and financial uncertainty is accompanied by a decline in aggregate GDP, \(Y\). In other words, uncertainty in both financial markets and the real economy rises during recessions.

\(\text{C.3. (Implication 3) Contagion and Spillover}\)

Our model implies information contagion and spillover. An adverse shock that directly affects only a small fraction of islands can generate a global recession on all islands through the endogenous information mechanism. Figure 4 illustrates the effects, where the arrows have the same meanings as in Figure 3. In Figure 4, an adverse shock to \(c\) on some islands has a negative spillover effect on all other islands. Of course, an adverse shock to \(b\) has a similar effect. This implication of our model is consistent with a large amount of anecdotal evidence that idiosyncratic firm-level shocks can be the origin of aggregate fluctuations (i.e., a microfoundation for aggregate shocks; see Gabaix (2011)).

Formally, we conduct a simple extension of our main model to allow for heterogeneity in \(b\) or \(c\) across islands. Let the information acquisition cost be \(b = b^H\) for a fraction of islands, \(j \in [0, \omega]\), and \(b = b^L\) for the remaining fraction of islands, where \(b^H > b^L\) and \(0 \leq \omega \leq 1\). Suppose that in equilibrium, information precision is given by \((\tau_s^*, \tau_q^*)\) for the first fraction of islands and by \((\bar{\tau}_s, \bar{\tau}_q)\) for the remaining fraction of islands. Then, aggregate endogenous TFP is given by

\[
A = \left[ \omega A \left( \frac{1}{\tau_s^* \tau_q^*} \right) + (1 - \omega) A \left( \frac{1}{\bar{\tau}_s \bar{\tau}_q} \right) \right]^{\frac{\eta}{\eta - 1}}
\]

and aggregate output \(Y\) is given by (25), where \(A = A(\tau_s, \tau_q^*)\) and \(\bar{A} = A(\bar{\tau}_s, \bar{\tau}_q^*)\).

Now we are able to formalize the contagion effect. For a given \(Z\) and \(c\), define \(b^*\) such that \(Z = Z(b^*, c)\), where function \(Z\) is given in Proposition 5. Suppose that \(b = b^L\) initially for all islands,

\[^{19}\text{Equivalently, we can define financial uncertainty as } SD[v_j|s_j, q_j] = \sqrt{\left(\frac{1}{2}\right)^2 Var[\varepsilon_j|s_j, q_j] + (1 - \frac{1}{2})^2 Var[a_j|s_j] = \sqrt{\left(\frac{1}{\tau_s + \tau_q}\right)^2 + (1 - \frac{1}{2})^2 \frac{1}{\tau_a + \tau_s}}.\]
where \( b^L \) is slightly lower than \( b^{**} \). By Proposition 5, the economy initially has two equilibria, where one equilibrium is that all islands are with the “good” equilibrium — the information precision for all islands is \( (\tau_s, \tau_q) = (\bar{\tau}_s, \tau_q^{**}) \). Consider now the case in which a small fraction of islands suffer a shock in the sense that their information acquisition cost increases slightly to \( b = b^H \) (which is slightly above \( b^{**} \)). Then the islands suffering the shock inevitably fall into the “bad” equilibrium with \( (\tau_s, \tau_q) = (\bar{\tau}_s, \tau_q^*) \). This decreases \( Y \) by (31). Because \( Y \) is reduced, all other islands are affected and can also inevitably fall into the “bad” equilibrium (by Proposition 3). That is, the unique “bad” equilibrium for the whole economy can be the outcome. In other words, financial market efficiency, real allocative efficiency, and the expected output in value (i.e., real GDP, \( P_jY_j \)) on all islands will all go down. Again, a numerical illustration of this result will be provided in Section V.

\[
\begin{align*}
\text{Some islands} & \quad \uparrow \tau_q \quad \downarrow \tau_s \quad \downarrow Y \\
\text{Other islands} & \quad \uparrow \tau_q \quad \downarrow \tau_s
\end{align*}
\]

Figure 4. Information contagion.

C.4. (Implication 4) Cross-Sectional Implications

Our general equilibrium model with production and a continuum of assets is particularly useful for studying asset price comovements. Empirical studies have established several interesting but puzzling patterns of comovements, summarized below.

i) A negative relation exists between the degree of comovement of stock prices in a sector and the informativeness of the stock prices (e.g., Durnew et al. (2003)). Stock prices move together more in poor economies than in rich economies (e.g., Morck, Yeung, and Yu (2000)).

ii) There is a decline in comovement of asset prices across sectors over time (e.g., Campbell et al. (2001)).

iii) Correlations between U.S. stocks and the aggregate U.S. market are much higher for downside moves than for upside moves (e.g., Ang and Chen (2002)).

iv) Industries with larger firm-specific variation in stock returns have higher economic efficiency of corporate investment (e.g., Durnew, Morck, and Yeung (2004)).
We show how our model can help shed light on these intriguing empirical regularities. The intuition is easy to understand. In our model, an individual asset price \( q_j \) is effectively driven by three components: aggregate productivity \( Z \), the firm’s signal \( s_j = a_j + e_j \), and informed traders’ signals \( x_j^i = \varepsilon_j + q_j^i \). The aggregate price index is instead driven by the aggregate productivity \( Z \) alone by the law of large numbers. When the signals \( s_j \) and \( x_j^i \) become more precise, the individual price \( q_j \) becomes more responsive to idiosyncratic shocks \( a_j \) and \( \varepsilon_j \) and relatively less responsive to the aggregate shock \( Z \); therefore, the correlation between an individual asset price and the aggregate price index becomes lower. At the same time, the efficiency of resource allocation, characterized by the endogenous TFP \( A \), becomes higher and the aggregate output increases. In short, a lower degree of comovement of asset prices as well as a higher efficiency of resource allocation is expected to be accompanied by higher aggregate output.

Formally, for simplicity and to sharply deliver the message, we study two extreme cases of the model. Consider two countries that differ only in information acquisition costs. We assume that country I has extremely high information acquisition costs, say, \( b^I = c^I = \infty \), whereas country II has information acquisition costs that are close to zero, namely, \( b^{II} \to 0 \) and \( c^{II} \to 0 \). Moreover, if agents acquire information, their signals are perfectly informative, namely \( \tau_s = \tau_x = \infty \); otherwise they obtain useless signals. We also assume a reasonable parameter condition \( \tau_n > (\frac{1}{\theta})^2 \vartheta \), where \( \vartheta = (1 - \frac{1}{\theta})^2 \tau_a^{-1} + (\frac{1}{\theta})^2 \tau_\varepsilon^{-1} \). Then, the asset prices in country I and country II, respectively denoted by \( q_j^I \) and \( q_j^{II} \), are given by

\[
q_j^I = q_0^I + \frac{\Theta^2}{\theta - \eta \Theta} \log A + \frac{\theta \Theta}{\theta - \eta \Theta} z + \gamma \left[ \left( 1 - \frac{1}{\theta} \right)^2 \tau_a^{-1} + \left( \frac{1}{\theta} \right)^2 \tau_\varepsilon^{-1} \right] n_j
\]

\[
q_j^{II} = q_0^{II} + \frac{\Theta^2}{\theta - \eta \Theta} \log A + \frac{\theta \Theta}{\theta - \eta \Theta} z + \Theta \left[ \left( 1 - \frac{1}{\theta} \right) a_j + \frac{1}{\theta} \varepsilon_j \right],
\]

where \( q_0^I \) and \( q_0^{II} \) are two constants which do not depend on \( z \). Define \( q^I = \int q_j^I dj \) and \( q^{II} = \int q_j^{II} dj \). We have \( \text{corr}(q_j^I, q^I) = \frac{\theta \Theta}{\theta - \eta \Theta} \sqrt{\tau_z^{-1}} \) and \( \text{corr}(q_j^{II}, q^{II}) = \frac{\theta \Theta}{\theta - \eta \Theta} \sqrt{\tau_z^{-1}} \), where \( \tau_z^{-1} \) is the variance of aggregate shock \( z \). So \( \text{corr}(q_j^I, q^I) > \text{corr}(q_j^{II}, q^{II}) \). For a given realization \( Z \), the endogenous aggregate TFP of the two countries satisfies \( A^I < A^{II} \) and the aggregate output satisfies \( Y^I < Y^{II} \).

Similarly, we can consider one country with two types of islands. The setup for the two types of islands is the same as that for the two types of countries above. Assume that the fraction of the first type of islands is \( \omega \). Then, the asset prices on type-I islands and type-II islands are respectively given by

\[
q_j^I = q_0^I + \frac{\Theta^2}{\theta - \eta \Theta} \log A + \frac{\theta \Theta}{\theta - \eta \Theta} z + \gamma \left[ \left( 1 - \frac{1}{\theta} \right)^2 \tau_a^{-1} + \left( \frac{1}{\theta} \right)^2 \tau_\varepsilon^{-1} \right] n_j
\]
and 
\[ q_j^I = q_0^I + \frac{\Theta^2}{\theta - \eta \Theta} \log A + \frac{\theta \Theta}{\theta - \eta \Theta} z + \Theta \left[ \left( 1 - \frac{1}{\theta} \right) a_j + \frac{1}{\theta} z_j \right], \]

where the endogenous TFP \( A \) of the country is given by (31), and its aggregate output \( Y \) is given by (25). When \( \omega \) increases, \( A \) decreases and therefore asset prices on all islands and aggregate output \( Y \) fall together. Define the aggregate price index as 
\[ q = \omega \int q_j^I dj + (1 - \omega) \int q_j^II dj. \]

The average correlation is computed as 
\[ \frac{\frac{\theta \Theta}{\theta - \eta \Theta} \sqrt{\tau_z}}{\sqrt{\left( \frac{\theta \Theta}{\theta - \eta \Theta} \right)^2 + \gamma^2 \theta^2 \tau_n^{-1}}} + (1 - \omega) \frac{\frac{\theta \Theta}{\theta - \eta \Theta} \sqrt{\tau_z}}{\sqrt{\left( \frac{\theta \Theta}{\theta - \eta \Theta} \right)^2 + \Theta^2 \theta^2}}, \]

which is increasing in \( \omega \). It is also true that \( \text{corr}(q_j^I, \int q_j^I dj) > \text{corr}(q_j^II, \int q_j^II dj) \).

The above model results explain the four empirical patterns listed at the beginning of this subsection. First, sector I (type-I islands), relative to sector II, has a higher degree of asset price comovement by \( \text{corr}(q_j^I, \int q_j^I dj) > \text{corr}(q_j^II, \int q_j^II dj) \) and also a lower degree of financial price informativeness by \( \tau_q^* < \tau_q^{**} \). Second, the improvement of information technology may correspond to a decrease in \( \omega \) over time for a country, and hence our model implies that comovement in asset prices declines over time. Third, economic downside moves may correspond to periods with a higher \( \omega \), so asset price comovement is higher in such periods. Fourth, country I with a lower GDP has a higher degree of asset price comovement than country II. Sector I, which has a higher degree of asset price comovement, has lower investment efficiency by \( A < \bar{A} \).

The puzzling empirical facts on asset price comovement, which are difficult to explain with traditional asset pricing theory, have inspired a number of theoretical studies. Notably, Peng and Xiong (2006) study a pure exchange economy and show that their model can explain facts i) and ii). Our model with a production economy complements their work. By linking asset price comovements to information production and investment efficiency in a production economy, we are able to explain the two additional facts iii) and iv).

**D. Model Extensions**

In this section, we conduct two extensions on our macroeconomic model.

**D.1. Heterogeneity and Multiplicity**

In this subsection, we extend our macroeconomic model by considering heterogeneity of firms and studying its effect on equilibrium multiplicity. Interestingly, we find that heterogeneity can actually increase, rather than reduce, the possibility of multiple equilibria in our model. This result is in sharp contrast to the types of coordination failure studied in other models, which have shown that heterogeneity can make multiple equilibria disappear.\(^\text{20}\)

\(^\text{20}\)See the discussions on Ball and Romer (1991), Morris and Shin (1998), and Schaal and Taschereau-Dumouchel (2015) in the literature review of the paper.
Formally, we consider the case in which there is heterogeneity in $b_j$ (the fixed cost of a firm’s information acquisition). In our NBER working paper version of Benhabib, Liu, and Wang (2018), we also study heterogeneity in the observable part of firm-specific productivity and the results are similar. Let $b_j$ be drawn from a continuous distribution with cumulative density function (c.d.f.) $G(\cdot)$ in support $[0, \infty)$. This implies that in equilibrium a fraction of islands will have less precise information (i.e., $(\tau_s, \tau_q) = (\tau_s, \tau_q^*)$) and the other fraction of islands will have more precise information (i.e., $(\tau_s, \tau_q) = (\tilde{\tau}_s, \tau_q^*)$). Let us denote the first fraction by $!$, and then the endogenous TFP, $A$, is given by (31). Thus, aggregate output $Y$ is a function of $A$. In the same spirit as Proposition 3, we find that there are three types of islands in equilibrium.

**Lemma 3** Suppose that $\omega$ is given and thus so are $A$ and $Y$ for a realized $Z$. In equilibrium, for islands with $b_j < b^*$, the equilibrium outcome is unique with $(\tau_s, \tau_q) = (\tau_s, \tau_q^*)$; for islands with $b_j > b^{**}$, the outcome is also unique with $(\tau_s, \tau_q) = (\tilde{\tau}_s, \tau_q^*)$; and for islands with $b^* \leq b_j \leq b^{**}$, there are multiple equilibria with $(\tau_s, \tau_q) = (\tau_s, \tau_q^*)$ or $(\tilde{\tau}_s, \tau_q^{**})$, where $b^*$ and $b^{**}$ are determined by

$$
\frac{1}{\vartheta} \left( \frac{A(\tau_s, \tau_q^*)}{A} \right)^{\frac{1}{\varpi - \eta}} Y - b^* = \frac{1}{\vartheta} \left( \frac{A(\tilde{\tau}_s, \tau_q^*)}{A} \right)^{\frac{1}{\varpi - \eta}} Y
$$

and

$$
\frac{1}{\vartheta} \left( \frac{A(\tau_s, \tau^{**}_q)}{A} \right)^{\frac{1}{\varpi - \eta}} Y - b^{**} = \frac{1}{\vartheta} \left( \frac{A(\tilde{\tau}_s, \tau_q^{**})}{A} \right)^{\frac{1}{\varpi - \eta}} Y,
$$

respectively.

The intuition behind Lemma 3 is very similar to that behind Proposition 3. For a given $Y$ and $Z$, when $b_j$ is sufficiently low, the dominant strategy for firm $j$ is to acquire information (i.e., $\tau_s = \tau_s^*$) even if the financial market is less informative (i.e., $\tau_q = \tau_q^*$). A similar argument applies for other ranges of $b_j$.

Lemma 3 essentially shows how the two thresholds $b^*$ and $b^{**}$ are determined for a given $\omega$. An equilibrium means a fixed-point problem between $(b^*, b^{**})$ and $\omega$. Proposition 6 follows.

**Proposition 6** When there is heterogeneity in $b_j \in [0, \infty)$ across firms, for a realized $Z$ there are always multiple equilibria in which $\omega$, the endogenous TFP, and aggregate output are driven by a sunspot variable $0 \leq s \leq 1$, such that

$$
\omega = sG(b^*) + (1 - s)G(b^{**})
$$

where $b^*$ and $b^{**}$ in turn satisfy (32) and (33), respectively. The endogenous TFP is given by (31) and the aggregate output is given by $Y = Y(A; Z)$ according to the formula in (25).

Proposition 6 illustrates that heterogeneity in $b_j$ increases the likelihood of multiple equilibria.
In fact, Proposition 5 corresponds to the case of no heterogeneity in $b_j$, in which multiple equilibria occur only under an intermediate level of realized $Z$ and feature two symmetric equilibria (i.e., $\omega = 0$ or $\omega = 1$). In contrast, Proposition 6 shows that for any realized $Z$ there are multiple equilibria and for a given $Z$ the multiple equilibria feature a continuum of $\omega$ driven by sunspots.

The reason for this intriguing result is that there are two layers of coordination problems in our model. First, given other islands’ information decisions, within an island there exists a coordination problem between the firm and the financial market on that island. The second coordination problem occurs across islands due to the Dixit-Stiglitz demand externality. Heterogeneity in the information acquisition cost reduces the incentive of the firm on a particular island to coordinate with firms on other islands. So information production across islands will be less synchronized. However, enough heterogeneity in the information acquisition cost naturally divides islands into three types as shown in the partial equilibrium of Proposition 3. As a result, two equilibria will always exist on some islands — islands on which the information acquisition cost $b_j$ falls into a range such that the partial equilibrium in Proposition 3 has multiple (two) equilibria. Since the total fraction of islands with the “good” equilibrium is indeterminate, the aggregate economy thus features a continuum of equilibria.

**D.2. Investors Holding a Portfolio**

In Section III.A, we assume that an investor can trade in only one financial market (asset). Now we show that our model insight holds if investors can hold a portfolio with access to financial assets on all islands.

For expository clarity, we slightly modify the setup of the macroeconomic model in Section III.A by letting there be $j = 1, 2, 3, \ldots, J$ discrete islands. The Dixit-Stiglitz production function in (18) is alternatively assumed to be

$$Y = J^{-\frac{1}{\sigma}} \left[ \sum_{j=1}^{J} c_j \frac{1}{\sigma} Y_j^{\frac{\sigma-1}{\sigma}} \right]^{\frac{\sigma}{\sigma-1}},$$

where the normalization follows the standard macroeconomic literature such as Jaimovich and Floetotto (2008). The demand schedule for good $j$ is then given by $Y_j = \frac{1}{J} \left( \frac{1}{J} \right)^{\frac{\sigma}{\sigma-1}} c_j Y$. Hence, as before, $v_j = \frac{1}{\sigma} c_j + (1 - \frac{1}{\sigma}) (z + a_j) + \eta (1 - \frac{1}{\sigma}) k_j + \frac{1}{\sigma} \log J$.

There is still a continuum of investors with unit mass. Investor $i$ maximizes his utility (20) subject to constraint (21), in which the payoff $D^i$ from financial market trading becomes

$$D^i = \sum_{j=1}^{J} m^i_j (v_j - q_j) - \sum_{j=1}^{J} c^i_j,$$
where \( m^i_j \) is his position on asset \( j \) and \( c_j \) is an indicator function such that \( c_j^i = c \) if he acquires information about \( \varepsilon_j \) and \( c_j^i = 0 \) otherwise. Hence, the utility maximization problem can be transformed into

\[
\max -E \left[ \prod_{j=1}^{J} \exp \left( -\gamma \left[ m^i_j (v_j - q_j) - c^i_j \right] \right) \right].
\]  

(34)

Because \( v_j \) and \( q_j \) are independent across islands, the investor’s decision on all islands together, \( \{ m^i_j \} \), is the same as the decision on each island separately. The first-order condition of (34) implies

\[
m^i_j = \begin{cases} 
\frac{\mathbb{E}[v_j|s_j, q_j, x^i_j] - q_j}{\gamma \text{Var}[v_j|s_j, q_j, x^i_j]} & \text{if } c^i_j = c \\
\frac{\mathbb{E}[v_j|s_j, q_j] - q_j}{\gamma \text{Var}[v_j|s_j, q_j]} & \text{if } c^i_j = 0
\end{cases} = m^I_j,
\]

which is exactly the same as the trading (asset holding) decision of a speculator in Section I. It is also easy to show that the results of information acquisition decisions for speculators in Section II apply here. The results for firms’ information acquisition and the aggregate economy equilibrium keep the same after some normalization (see our NBER working paper version of Benhabib, Liu, and Wang (2018)).

IV. The Dynamic Model

In this section, we extend the static model to an OLG framework. The OLG model provides a dynamic equilibrium setting to study the process of saving and capital accumulation. The exogenous endowment \( W_0 \) in the static model is now endogenized. The equilibrium is therefore dynamically linked across periods through savings — the nature of equilibrium in the next period endogenously depends not only on the aggregate productivity shock \( Z \) in that period but also on aggregate output in the current period.

We derive three additional economic insights. First, we show that the dynamic model possibly has two steady-state equilibria, which means that the economy can exhibit self-fulfilling uncertainty traps. Second, when we study the transitional dynamics under a permanent negative shock, the dynamic model characterizes a two-stage economic crisis. Third, in the dynamic model, the aggregate shock \( Z \) is endogenously revealed through information aggregation of prices in the spirit of Hayek (1945), rather than assumed to be constant and publicly observable as in the static model.

A. Setup

Agents. In each period, there are three types of agents: investors (who were workers in the last period), entrepreneurs, and workers. There is a continuum of \([0, 1] \times [0, 1]\) investors (workers) and a continuum of \([0, 1]\) entrepreneurs. Each worker is endowed with one unit of time. A worker

\footnote{For simplicity, we assume that entrepreneurs survive for only one period and in each period a new generation of entrepreneurs is born.}
supplies labor for a wage when he is young, and saves up his wage as capital and becomes an investor when he is old. An investor earns income on his capital and then consumes. Each entrepreneur is a monopoly producer for an intermediate good on one island; he earns a profit and then consumes.

**Production.** Production of an intermediate good needs the inputs of capital and labor subject to information frictions as in the baseline model. Specifically, the production function of intermediate good \( j \) is

\[
y_{jt} = Z_t A_{jt} \left( K_{jt}^{\eta} N_{jt}^{1-\eta} \right),
\]

where \( K_{jt} \) is the capital input, which fully depreciates after production, \( N_{jt} \) is the labor input, and \( \eta \in (0, 1) \). There is a final good production sector as in the static model, with the production function

\[
y_t = \left[ \int \epsilon_{jt}^{\frac{1}{\theta}} Y_{jt}^{\theta-1} \, dj \right]^{\frac{\theta}{\theta-1}},
\]

where \( j \in [0, 1], \theta > 1 \) is the elasticity of substitution between intermediate capital goods, and \( \epsilon_{jt} \) measures the demand shock to intermediate good \( j \). Denote \( a_{jt} \equiv \log A_{jt} \) and \( \varepsilon_{jt} \equiv \log \epsilon_{jt} \). The price of the final good is normalized as the numeraire price in each period \( t \).

**Timeline.** In each period \( t \), there are five stages.

**Stage 1:** The old generation of workers become investors who possess capital that is carried over from the last period. A new generation of workers and a new generation of entrepreneurs are born.

**Stage 2:** Entrepreneurs and investors simultaneously make their information acquisition decisions as in Section II. Entrepreneur \( j \) acquires information about productivity shock \( a_{jt} \) and investors acquire information about demand shocks \( \{\varepsilon_{jt}\} \).

**Stage 3:** As in the timeline in the baseline model of Section I, an entrepreneur first discloses his signal to the financial market, and then financial market trading takes place, and then entrepreneurs make their investment decisions.

**Stage 4:** Production output is realized. Output is divided among workers (wages), investors (capital returns), and entrepreneurs (profits). The payoffs of financial contracts are delivered. Investors and entrepreneurs consume and then die.

**Stage 5:** Workers receive private signals about the aggregate productivity shock \( Z_{t+1} \) in the next period which is realized but not public information. Workers trade their capital (wages) and bonds among themselves. The capital price and the return on bonds, \( R_{ft+1} \), are realized. Workers then proceed to the next period.

**B. Equilibrium**
At stage 5 of period $t - 1$, workers invest their wage income in capital and bonds based on their dispersed information about $Z_t$. A typical worker $i$ faces the budget constraint

$$1 \cdot K^i_t + (1/R_{ft}) \cdot B^i_t = W_{t-1},$$

where $W_{t-1}$ is his wage income, $K^i_t$ is the number of units of capital, and $B^i_t$ is the number of units of bonds that he invests in. One unit of consumption good at this stage can be transformed into one unit of capital and hence the price of capital is one. One unit of capital allows its owner to obtain the rental return $R_f$ in the next period $t$. The bond is traded at the discounted price $1/R_{ft}$ and hence the return on the bond is $R_{ft}$; in other words, $R_{ft}$ is the intertemporal interest rate between $t - 1$ and $t$. Each worker receives a noisy private signal about $Z_t$. Since there is no aggregate noise trading, $Z_t$ is revealed through the bond price $1/R_{ft}$ as in Vives (2014) and Benhabib, Liu, and Wang (2016a). It must also be true that $R_{ft} = R_f$ in equilibrium. Since the net bond supply is zero, the aggregate capital in the next period $t$ is $K_t = W_{t-1} \times 1 = W_{t-1}$.

In period $t$, investor $i$, who was a worker in the last period, starts with $K^i_{t-1}$ units of capital and $B^i_{t-1}$ units of bonds. At stage 3, investors trade risky assets with payoff $v_{jt} = \log(Y_{jt}P_{jt})$ at prices $q_{jt}$. Hence, when trading risky assets, an investor’s problem is

$$\max_{C^i_t, m^i_{jt}} \mathbb{E}[\exp\{-\gamma (C^i_t - z^i_t c)\} | \mathcal{I}^i_t]$$

s.t. $C^i_t = R_f K^i_{t-1} + (v_{jt} - q_{jt}) m^i_{jt} + B^i_t$,

where $C^i_t$ is investor $i$’s consumption, $K^i_{t-1}$ is his capital purchased in the previous period, $B^i_t$ is his total purchase of bonds, $m^i_{jt}$ is his position on risky asset $j$, and $c$ is the information acquisition cost as in the static model. The term $z^i_t$ is an indicator function, which equals 1 if the investor acquires information and 0 otherwise. Because $Z_t$ is revealed by $1/R_{ft}$ in the last period $t - 1$, the information set $\mathcal{I}^i_t$ is $\{s_{jt}, q_{jt}, x^i_j, Z_t\}$ if acquiring information and $\{s_{jt}, q_{jt}, Z_t\}$ otherwise, where $s_{jt}$ is entrepreneur $j$’s signal and disclosure about $a_{jt}$ and $x^i_j$ is investor $i$’s signal about $\varepsilon_{jt}$. For simplicity and tractability, we assume in the dynamic model that information acquisition costs ($b$ and $c$) are direct utility costs to agents.

At the production stage, entrepreneur $j$’s problem is to solve

$$\max_{K_{jt}, N_{jt}} \mathbb{E}[P_{jt} Y_{jt} - W_i N_{jt} - R_f K_{jt} | \mathcal{I}_{jt}],$$

(37)

where $P_{jt} = \left(\frac{c_{jt} Y_{jt}}{Y_{jt}}\right)^{\frac{1}{2}}$, $Y_{jt}$ is given by (35), and $W_i$ is the wage. The information set is $\mathcal{I}_{jt} = \{s_{jt}, q_{jt}, W_t, R_f, Z_t\}$. Denote by $\tau_{st}$ the precision of signal $s_{jt}$ and by $\tau_{qt}$ the precision of financial price signal $q_{jt}$. Lemma 4 follows.
Lemma 4 Given \( \tau_{st} \) and \( \tau_{qt} \), the dynamics of the economy are characterized by

\[
Y_t = Z_t A_t K_t^{\eta}, \\
K_{t+1} = W_t = (1 - \frac{1}{\theta})(1 - \eta)Y_t, \\
A_t = \exp \left( \frac{1}{2} (\theta - 2) \frac{1}{\tau_a} - \frac{1}{2} \frac{(\theta - 1)^2}{\tau_a + \tau_{st}} - \frac{1}{2} \frac{1}{\theta \tau_a + \tau_{qt}} \right).
\]

To determine \( \tau_{st} \) and \( \tau_{qt} \), we need to study the information acquisition problem of entrepreneurs and investors. Similar to (15), information acquisition of investors gives

\[
e^{\gamma c} = \sqrt{\frac{(1 - \frac{1}{\theta})^2 \frac{1}{\tau_a + \tau_{st}} + \left( \frac{1}{\theta} \right)^2 \frac{1}{\tau_a + \tau_{qt}}}{(1 - \frac{1}{\theta})^2 \frac{1}{\tau_a + \tau_{st}} + \left( \frac{1}{\theta} \right)^2 \frac{1}{\tau_a + \tau_{st} + \tau_{qt}}}}.
\]

Hence, similar to Proposition 1, \( \tau_{qt} \) is a function of \( \tau_{st} \) and \( c \), with comparative statics \( \frac{\partial \tau_{qt}}{\partial \tau_{st}} > 0 \) and \( \frac{\partial \tau_{qt}}{\partial c} < 0 \). The information acquisition problem of entrepreneurs gives similar results as Propositions 2 and 3. We still focus on symmetric equilibria, in which \((\tau_{st}, \tau_{qt}) = (\tau_s, \tau_q^*)\) or \((\tau_s, \tau_q^*)\). Define

\[
\xi \equiv \left[ \frac{A(\tau_s, \tau_q)}{A(\tau_s, \tau_q)} \right]^{\theta - 1} = \exp \left[ \frac{1}{2} (\theta - 1)^3 \left( \frac{\tau_s - \tau_q}{(\tau_a + \tau_s)(\tau_a + \tau_q)} \right) \right] > 1, \quad \bar{A} = A(\tau_s, \tau_q^*), \quad \text{and} \quad \bar{A} = A(\tau_s, \tau_q^*).
\]

Then we find two thresholds \( \bar{K} \) and \( \bar{K} \), which are functions of \( Z_t \) and respectively solve

\[
\frac{1}{\theta} \xi Y(Z_t, A, K) - b = \frac{1}{\theta} Y(Z_t, \bar{A}, \bar{K})
\]

and

\[
\frac{1}{\theta} Y(Z_t, \bar{A}, \bar{K}) - b = \frac{1}{\theta} \xi Y(Z_t, A, K),
\]

where \( Y(Z_t, A_t, K_t) = Z_t A_t K_t^{\eta} \). Proposition 7 follows.

Proposition 7 For a given \( Z_t \), there is a unique equilibrium \((\tau_{st}, \tau_{qt}) = (\tau_s, \tau_q^*)\) when \( K_t > \bar{K} \); there is a unique equilibrium \((\tau_{st}, \tau_{qt}) = (\tau_s, \tau_q^*)\) when \( K_t < \bar{K} \); and there are multiple (two) equilibria with \((\tau_{st}, \tau_{qt}) = (\tau_s, \tau_q^*)\) or \((\tau_s, \tau_q^*)\) when \( \bar{K} \leq K_t \leq \bar{K} \), where \( \bar{K} \) and \( \bar{K} \) are two thresholds, decreasing functions of \( Z_t \).

Proposition 7 implies that for the dynamic model, whether a unique equilibrium or multiple equilibria exist depends not only on the realization of shock \( Z_t \) in the current period but also on the capital stock \( (K_t = W_{t-1}N_{t-1}) \) in the last period. In other words, the nature of the equilibrium is path-dependent. This is in contrast to the result in Proposition 5 for the static model, where the existence of a unique equilibrium or multiple equilibria depends only on the realization of shock \( Z \).
Based on Lemma 4 and Proposition 7, we can find the law of motion for capital:

\[
K_{t+1} = \begin{cases} 
(1 - \frac{1}{\bar{\gamma}})(1 - \eta)Z_t \bar{A} K_t^{\eta} & \text{if } K_t \geq \bar{K}(Z_t) \\
(1 - \frac{1}{\bar{\gamma}})(1 - \eta)Z_t \bar{A} K_t^{\eta} & \text{if } K_t \leq \bar{K}(Z_t).
\end{cases} \tag{38}
\]

**Proposition 8 (Steady States)** Suppose that \( Z_t = Z \), a constant. If \( Z > Z^{**} \) or \( Z < Z^* \), there is a unique steady-state equilibrium; if \( Z^* \leq Z \leq Z^{**} \), there are two steady-state equilibria, where the two thresholds are \( Z^* = \left[ \frac{\left( \frac{1}{1 - \mu} \right)^{1 - \eta}}{1 - \eta} \right] \frac{1}{\bar{A}} \) and \( Z^{**} = \left[ \frac{\left( \frac{1}{1 - \mu} \right)^{1 - \eta}}{1 - \eta} \right] \frac{1}{\bar{A}} \).

Proposition 8 highlights self-fulfilling uncertainty traps in the dynamic economy. Figure 5 illustrates Proposition 8. Two remarks are in order. First, even if we impose an equilibrium selection to choose the “good” equilibrium in each period (in which case the jump point in Figure 5 is unique at \( K_t = \bar{K} \)), there are still possibly multiple steady-state equilibria. Second, while Figure 5 indicates the existence of two possible equilibrium paths starting in the range \((\bar{K}, \bar{K})\), nothing prevents the equilibrium from switching between the two branches of capital accumulation in that range of \( K_t \). The coordination problem for agents, whether to acquire high or low information (i.e., \((\tau_{st}, \tau_{qt}) = (\bar{\tau}_s, \bar{\tau}_q^{**}) \) or \((\bar{\tau}_s, \bar{\tau}_q^{*}) \)), is independent across periods since a new generation of agents replaces the old generation each period. Equilibrium switches between periods can be driven by a stochastic sunspot or sentiment process such as a Markov chain, or animal spirits.\(^{22}\)

![Figure 5. Two possible steady-state equilibria.](image-url)

Next, we examine the transitional dynamics. Suppose that initially \( Z_t = Z \), which is constant and a bit higher than \( Z^{**} \), and suddenly at \( t = t_0 \) a permanent negative shock hits \( Z_t \). Proposition 9 gives the transitional dynamics under a permanent negative shock.

**Proposition 9 (Transitional Dynamics)** Suppose that initially \( Z_t = Z > Z^{**} \) and the economy is in the steady state, and at \( t = t_0 \) a negative shock hits \( Z_t \) resulting in \( Z_t = Z' < Z \). If the shock

\(^{22}\)See, for example, Benhabib, Dong, and Wang (2018).
is small enough such that $Z' > Z^{**}$, the transitional dynamics of $K_t$ are given by 38(a) for $t > t_0$; if the shock is medium-sized such that $Z^* < Z' < Z^{**}$, the transitional dynamics of $K_t$ can be 38(a) for $t_0 < t < t_1$ and 38(b) for $t \geq t_1$, where $t_1$ is the time point of equilibrium switching.

Figure 6 illustrates Proposition 9. When the shock is small, the dynamic economy still has a unique “good” steady-state equilibrium. However, when the shock is medium-sized, it triggers a regime change: from the existence of a unique “good” steady-state equilibrium to the existence of two steady-state equilibria. The case of a medium-sized shock characterizes a two-stage economic crisis. The negative shock itself does not cause a big decline in economy activity at the beginning. After the shock, capital accumulation is initially along the unique path (i.e., the upper branch toward the new “good” steady-state equilibrium in Figure 6) and the capital stock is declining over time but the recession is mild. However, once the capital stock $K_t$ has declined to a certain point such that $K_t \leq \bar{K} \left( Z' \right)$, the second path of equilibrium is opened. A sunspot or sentiment can suddenly switch the equilibrium path to the lower branch, in which case a surge in real uncertainty and financial uncertainty accompanied by a big drop in output strikes. Thereafter, the economy declines further and gradually converges to the new “bad” steady-state equilibrium. Numerical illustrations of the transitional dynamics will be provided in Section V.

![Figure 6. Transitional dynamics under a permanent negative shock on $Z_t$.](image)

**V. Numerical Illustrations**

Our analytic analysis in the previous sections has demonstrated that the information interplay between the real sector and the financial sector can have strong effects on the economy. Our model

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23 It is easy to show that if $Z' \in (Z^*, Z^{**})$ is not too high, the dynamics of $K_t$ enter the region of $K_t \leq \bar{K} \left( Z' \right)$ before the new “good” steady state is reached.
is too stylized to be calibrated with the data. We will therefore assign values to the parameters in our model to conduct numerical illustrations below.

Table I summarizes the parameter values chosen. We set the elasticity of substitution between intermediate goods, $\theta$, to 6 as in David, Hopenhayn, and Venkateswaran (2016). This implies that the gross markup is 15%. We set the degree of decreasing returns to scale of production $\eta$ to 0.8, consistent with the recent estimates in Gopinath et al. (2016). We set the risk (CARA) coefficient $\gamma$ to 8, considering that CARA can be calibrated as the relative risk aversion (RRA) divided by wealth and the wealth level of a typical investor in our model is GDP.\footnote{We thank one referee for suggesting this way of calibrating $\gamma$.} We borrow the unconditional residual uncertainty parameter from David et al. (2016), where $\tau_a = 4.9383$. We set $\bar{\tau}_s = 6.5746$, implying that a firm can reduce its residual uncertainty (standard deviation) on the productivity shock to 0.30 by paying the information acquisition cost. We set $\underline{\tau}_s = 3$, implying that the residual uncertainty in productivity equals 0.36 if a firm does not pay the information acquisition cost. We set $\tau_\varepsilon = 0.04$, implying that the contribution of demand shocks to firms’ sales volatility is around a half of that of productivity shocks along the line of Foster, Haltiwanger and Syverson (2008). For simplicity, we set the precision of informed traders’ signal $\tau_x$ to infinity, meaning that an informed trader can perfectly informed of the demand shock through his private signal. We set the common productivity $Z = 6.5$, the information acquisition cost for a firm $b = 0.03$, and the information acquisition cost for a financial trader $c = 0.105$ by considering that in equilibrium only a fraction of traders choose to acquire information. These parameter values lead to two self-fulfilling equilibria in our model.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\theta$</td>
<td>Elasticity of substitution between intermediate goods</td>
<td>6</td>
</tr>
<tr>
<td>$\gamma$</td>
<td>Risk (CARA) coefficient</td>
<td>8</td>
</tr>
<tr>
<td>$\eta$</td>
<td>Degree of decreasing returns to scale of production</td>
<td>0.8</td>
</tr>
<tr>
<td>$Z$</td>
<td>Common productivity shock</td>
<td>6.5</td>
</tr>
<tr>
<td>$\tau_a$</td>
<td>Precision of productivity shock prior</td>
<td>4.9383</td>
</tr>
<tr>
<td>$\tau_\varepsilon$</td>
<td>Precision of demand shock prior</td>
<td>0.04</td>
</tr>
<tr>
<td>$b$</td>
<td>Information acquisition cost of the real side</td>
<td>0.03</td>
</tr>
<tr>
<td>$c$</td>
<td>Information acquisition cost of financial markets</td>
<td>0.105</td>
</tr>
<tr>
<td>$\tau_s$</td>
<td>Low precision of signals of the real side</td>
<td>3</td>
</tr>
<tr>
<td>$\bar{\tau}_s$</td>
<td>High precision of signals of the real side</td>
<td>6.5746</td>
</tr>
<tr>
<td>$\tau_x$</td>
<td>Precision of informed traders’ signal</td>
<td>$\infty$</td>
</tr>
</tbody>
</table>

Table I: Parameter Values

Table II summarizes the key results of the two self-fulfilling equilibria in Section III. First, both aggregate output and investment fall dramatically (by 58% and 58%, respectively) when
the economy falls into the “bad” equilibrium. Second, information production from the financial sector and that from the real sector are both lower in the “bad” equilibrium than in the “good” equilibrium. The firms and financial traders face productivity shocks with a posterior standard deviation of $(\bar{\tau}_s + \tau_o)^{-\frac{1}{2}} = 0.2947$ in the “good” equilibrium and $(\bar{\tau}_s + \tau_o)^{-\frac{1}{2}} = 0.3549$ in the “bad” equilibrium. The financial price can reduce the posterior standard deviation of firm demand shocks to $(\tau_q^* + \tau_o)^{-\frac{1}{2}} = 3.0789$ for the “good” equilibrium but to only $(\tau_q^* + \tau_o)^{-\frac{1}{2}} = 3.7079$ for the “bad” equilibrium. These numbers imply a 20% increase in financial uncertainty and a 20% increase in real uncertainty from the “good” equilibrium to the “bad” equilibrium. Third, the resulting information production declines have important consequences for allocation efficiency. The endogenous TFP decreases by about 16%. To understand this decline, we compute two alternative counterfactual endogenous TFP. We first compute $A(\bar{\tau}_s, \tau_q^*)$, the level of endogenous TFP when only the quality of the information provided by the financial market deteriorates while the quality of the information provided by firms stays at the level $\bar{\tau}_s$. We find that TFP would decrease by about 13%. The other 3% decline in the endogenous TFP is due to the reduction in firms’ information production as indicated by $A(\bar{\tau}_s, \tau_q^{**})$, the level of endogenous TFP that the economy would obtain when only the quality of the information provided by firms deteriorates while the quality of the information provided by the financial market stays at the level $\tau_q^{**}$.

<table>
<thead>
<tr>
<th>$\tau_s$</th>
<th>“Good” equilibrium</th>
<th>“Bad” equilibrium</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$\bar{\tau}_s = 6.5746$</td>
<td>$\bar{\tau}_s = 3$</td>
</tr>
<tr>
<td>$\tau_q$</td>
<td>$\tau_q^{**} = 0.0655$</td>
<td>$\tau_q^* = 0.0327$</td>
</tr>
<tr>
<td>GDP (Y)</td>
<td>1.3562</td>
<td>0.5657</td>
</tr>
<tr>
<td>Aggregate investment (K)</td>
<td>0.9041</td>
<td>0.3771</td>
</tr>
<tr>
<td>Endogenous TFP (A)</td>
<td>$A = 0.2262$</td>
<td>$A = 0.1899$</td>
</tr>
<tr>
<td>TFP under changing $\tau_q$ only ($A(\bar{\tau}_s, \tau_q^*)$)</td>
<td>0.1962</td>
<td></td>
</tr>
<tr>
<td>TFP under changing $\tau_s$ only ($A(\bar{\tau}_s, \tau_q^{**})$)</td>
<td>0.2189</td>
<td></td>
</tr>
</tbody>
</table>

Table II: Numerical Illustration for Two Self-Fulfilling Equilibria

As the nature of equilibrium depends crucially on the values of $Z$, $b$, and $c$, our second exercise is hence to conduct complete comparative statics to understand their impact on equilibria in Section III in a quantitative sense. We fix all other parameter values (given in Table I) but change one of $Z$, $c$, and $b$ each time and compute the equilibria accordingly. We report the results in Figure 7. Figure 7 has three columns, summarizing the comparative statics with respect to $Z$, $b$, and $c$. The first panel plots the equilibrium aggregate output, the second the posterior standard deviation of firms’ productivity shocks (given in (30)), and the third the posterior standard deviation of firms’ demand shocks inferred from financial prices (given in (29)).
The first column of Figure 7 shows that the equilibrium is unique if $Z > Z = 7.3701$ or $Z < Z = 6.2893$. Suppose that the economy initially starts with aggregate common productivity $Z = 7.5205$. A small drop in $Z$ by more than 2% would trigger a self-fulfilling crisis (see also Figure 2). In the second and third columns of Figure 7, the model generates two self-fulfilling equilibria when the information acquisition cost, $c$ or $b$, is at an intermediate level. Due to the binary information choice of the firm, aggregate output is insensitive to the change in $b$ under a given equilibrium. Similar to the effect of $Z$, if the initial level of $b$ or $c$ is close to its lower threshold for multiple equilibria, then a small shock (i.e., a small increase in $b$ or $c$) can cause a sudden large decline in aggregate output.

Our next exercise is to show information contagion in our model. Again we assume that all parameters are initially as given in Table I, except that we set $b = 0.0353$, slightly lower than the upper threshold of $b$ to have multiple (two) equilibria. According to Figure 7, the economy initially has two equilibria. Now we assume that a small fraction $\kappa = 5\%$ of firms suffer a shock in the sense that their information acquisition cost $b$ increases slightly to 0.0355, which means that a unique “bad” equilibrium takes hold in the economy of these islands by Figure 7. How about the other 95% of islands? The economy of the other 95% islands will inevitably fall into the “bad” equilibrium unless their acquisition cost $b$ decreases below 0.0347.

Finally, we give numerical illustrations for our OLG model, in particular, the results in Proposition 9. As production in the OLG model has inputs of both capital and labor, we set $\eta = 0.5$. 

Figure 7. Comparative statics analysis.
In order to quantitatively examine the effect of a small-sized shock versus a medium-sized shock on $Z_t$, we set $\tau_s = 5.5$. The values of other parameters are as given in Table I. Suppose that initially $Z_t = Z = 4.0961$. Based on Proposition 8, we find that the dynamic economy has a unique “good” steady-state equilibrium, in which $(\tau_{st}, \tau_{qt}) = (\tilde{\tau}_s, \tilde{\tau}_q^*)$. Suppose that the economy initially stays in this steady state for the first three periods, $t = 1$ to 3. Assume that in period $t = 4$ there is a sudden permanent shock on $Z_t$ such that $Z_t$ declines by 5% to $Z_t = Z' = 3.8913$. We examine what happens to the dynamic economy.

![Figure 8. Transitional dynamics under a permanent shock on $Z_t$. Left: a medium-sized shock of size $-5 \%$. Right: a small-sized shock of size $-2.5 \%$. Note: the initial value of each variable is normalized to 1.](image)

The left panels of Figure 8 show four phases of the dynamics. First, the shock has a direct impact. In period $t = 4$, the aggregate output $Y_t$ immediately drops by 5%, which is exactly the size of the shock. The capital stock $K_t$ declines by the same magnitude in the following period $t = 5$. Second, after the shock, the economy moves along a unique path, which is toward the new “good” steady state, until $t = 8$. The time between $t = 4$ to $t = 8$ corresponds to a time

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25 Even if we set $\eta = 0.8$ as we do earlier in this section, the quantitative result here would change little.
of a mild recession, in which aggregate output $Y_t$ and capital $K_t$ gradually decline further by less than 5%. Third, in period $t = 9$, because the capital stock is already sufficiently low and enters the region $K_t \leq \bar{K} (Z')$ as shown in Proposition 9, the second “bad” equilibrium path is opened, which gives room for equilibrium path switching. A sunspot or sentiment can suddenly switch the equilibrium path to the lower branch toward the “bad” steady state. Once that happens, the economy experiences a plunge with $Y_t$ falling by roughly 9% in one shot at $t = 9$. At the same time, real uncertainty and financial uncertainty surge, as shown in the panels in the third and fourth rows of Figure 8. Fourth, after that, the economy moves along the path toward the “bad” steady state, and $Y_t$ and $K_t$ decline further by around 8%.

In contrast, if the shock is small, e.g., $-2.5\%$ as shown in the right panels of Figure 8, then only the first and second phases take place but the third and fourth phases do not. After the shock, the economy moves along the unique path toward the new “good” steady state. The total decline in $Y_t$ and $K_t$ over the entire process is around 5%. Moreover, there is no increase in real uncertainty or financial uncertainty over the entire process.

VI. Conclusion

In this paper, we develop a model of informational interdependence between financial markets and the real economy. We endogenize financial and real uncertainty and show how they relate to aggregate economic activity. Information production in the real sector and that in the financial sector exhibit strategic complementarity. The key reason is that a financial price is a combination of firm disclosure and financial market price discovery. When a firm tries to maximize its monopoly profits in the real sector and speculators try to gain from arbitraging in financial markets, it is optimal for them to learn from each other. The mutual learning results in strategic complementarity in information production. In the general equilibrium, the amount of information available in the economy and the aggregate economic activity feed back into and reinforce each other. We derive a number of implications of our general equilibrium macro model. In the extension to the dynamic OLG setting, our model shows self-fulfilling uncertainty traps and characterizes a two-stage economic crisis.

We have studied information production in a model with monopolistic competition with a constant markup. A vast IO literature has also studied information acquisition and disclosure under an oligopolistic market structure (see, for example, Vives (1984, 2008) and Yang (2018)). Examining how different market structures affect the two-way feedback between financial markets and the real economy in general equilibrium will be an interesting topic for future research, as it could shed some light on how informational frictions affect markups, a major driving force for business cycles (Rotemberg and Woodford (1999)).
Appendix

A Main Notation of the Model

\( A_j, a_j, \tau_a \)  
Productivity shock of firm \( j \); \( \log A_j \equiv a_j \sim \mathcal{N}\left(-\frac{1}{2} \tau_a^{-1}, \tau_a^{-1}\right) \).

\( \varepsilon_j, \varepsilon_j, \tau_e \)  
Demand shock to intermediate good \( j \); \( \log \varepsilon_j \equiv \varepsilon_j \sim \mathcal{N}\left(-\frac{1}{2} \tau_e^{-1}, \tau_e^{-1}\right) \).

\( \eta \)  
Degree of decreasing returns to scale of production.

\( \theta \)  
Elasticity of substitution between intermediate goods.

\( \Theta \equiv -\frac{1}{\eta(1-\frac{1}{\theta})-1} \in (1, \theta) \).

\( Z \)  
Aggregate productivity shock.

\( Y, y \)  
Aggregate output of the final goods; \( y = \log Y \).

\( P \)  
Price of the final goods.

\( Y_j \)  
Output of intermediate capital good \( j \).

\( K_j, k_j \)  
Investment capital input of firm \( j \); \( k_j = \log K_j \).

\( P_j \)  
Price of intermediate good \( j \).

\( V_j, v_j \)  
Asset value or revenue of firm \( j \); \( v_j = \log V_j \).

\( \gamma \)  
Risk aversion (CARA) coefficient of investors.

\( n_j \)  
Demand of noise/liquidity traders in financial market \( j \).

\( s_j, \varepsilon_j, \tau_s, \tau_s, \tau_a \)  
Firm \( j \)'s signal about \( a_j \); \( s_j = a_j + \varepsilon_j \), where \( \varepsilon_j \sim \mathcal{N}(0, \tau_s^{-1}) \); \( \tau_s \in \{\tau_s^l, \tau_s^u\} \).

\( x^l_j, g^l_j, \tau_x \)  
Trader \( i \)'s signal about \( \varepsilon_j \); \( x^l_j = \varepsilon_j + g^l_j \), where \( g^l_j \sim \mathcal{N}(0, \tau_x^{-1}) \).

\( \lambda \)  
Proportion of informed traders.

\( q_j, \tilde{q}_j, \tilde{q}_j^q, \tau_q \)  
Trading price of \( v_j \); \( \tilde{q}_j = \frac{q_j - \beta_0 - \beta_1 \tilde{s}_j}{\beta_1} = \varepsilon_j + \tilde{g}^q_j \), where \( \tilde{g}^q_j \sim \mathcal{N}(0, \tau_q^{-1}) \).

\( b, c \)  
Information acquisition cost for a firm and a trader, respectively.

\( \Pi \)  
Ex ante expected profit of a firm.

\( A, A \)  
\( A = A(\tau_s, \tau_q) \), endogenous aggregate TFP.

\( K, K \)  
\( K = K(\tau_s, \tau_q; Z) \), aggregate investment in the economy.

\( \tilde{A}, A \)  
Upper and lower endogenous TFP; \( \tilde{A} = A(\tau_s, \tau_q^*) \) and \( A = A(\tau_s, \tau_q) \).

\( \bar{Z}, Z \)  
Upper and lower thresholds of \( Z \) for multiple equilibria in general equilibrium.

\( K_{jt}, K_t \)  
Capital input of firm \( j \) in the OLG model; \( \int_0^1 K_{jt}dj = K_t \).

\( N_{jt}, N_t \)  
Labor input of firm \( j \) in the OLG model; \( \int_0^1 N_{jt}dj = N_t \).

\( \bar{K}, K \)  
Upper and lower thresholds of \( K_t \) for multiple equilibria for a given \( Z_t \) in OLG.

\( Z^*, Z^* \)  
Upper and lower thresholds of \( Z_t \) for two steady-state equilibria in OLG.

\( R_t \)  
Rental return of capital in period \( t \) in OLG.

\( W_t \)  
Wage in period \( t \) in OLG.

\( R_{ft} \)  
Bond return or intertemporal interest rate between \( t - 1 \) and \( t \) in OLG.
\section*{B Proofs}

\textbf{Proof of Lemma 1:} Plugging (1) and (2) into (3) yields

\begin{equation}
    v_j = \frac{1}{\theta} \varepsilon_j + \left( 1 - \frac{1}{\theta} \right) (z + a_j) + \eta \left( 1 - \frac{1}{\theta} \right) k_j + \frac{1}{\theta} y_j,
\end{equation}

which depends on \( \varepsilon_j, a_j, \) and \( k_j \). However, speculators are certain about \( k_j \) but not \( \varepsilon_j \) and \( a_j \), because \( k_j \) is a function of signals \( s_j \) and \( q_j \) and thus speculators \textit{perfectly foresee} the investment decision of the firm. In solving (5), we find that \( m^{fi} = \frac{\mathbb{E}[v_j|s_j,q_j,x_i]}{\gamma \text{Var}[v_j|s_j,q_j]} \). Similarly, (6) gives \( m^{ui} = \frac{\mathbb{E}[v_j|s_j,q_j]-q_j}{\gamma \text{Var}[v_j|s_j,q_j]} \).

For an informed trader,

\begin{align*}
    \mathbb{E}[v_j|s_j,q_j,x_i] &= \frac{1}{\theta} \mathbb{E} \left[ \varepsilon_j|s_j,q_j,x_i \right] + \eta \left( 1 - \frac{1}{\theta} \right) k(s_j,q_j) + \frac{1}{\theta} y \left( 1 - \frac{1}{\theta} \right) \left[ z + \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \tau_a^{-1} \right) + \frac{\tau_s}{\tau_a + \tau_s} s_j \right],
\end{align*}

where

\begin{align*}
    \mathbb{E} \left[ \varepsilon_j|s_j,q_j,x_i \right] &= \frac{\tau_e}{\tau_e + \tau_s + \tau_q} \left( -\frac{1}{2} \tau_e^{-1} \right) + \frac{\tau_q}{\tau_e + \tau_s + \tau_q} \tilde{q}_j \text{ with } \tilde{q}_j(q_j,s_j) = q_j, \\
    \text{Var}[v_j|s_j,q_j,x_i] &= \left( \frac{1}{\theta} \right)^2 \text{Var} \left[ \varepsilon_j|s_j,q_j,x_i \right] + \left( 1 - \frac{1}{\theta} \right)^2 \frac{1}{\tau_a + \tau_s},
\end{align*}

where \( \text{Var} \left[ \varepsilon_j|s_j,q_j,x_i \right] = \frac{1}{\tau_e + \tau_s + \tau_q} \). For an uninformed trader,

\begin{align*}
    \mathbb{E}[v_j|s_j,q_j] &= \frac{1}{\theta} \mathbb{E} \left[ \varepsilon_j|s_j,q_j \right] + \eta \left( 1 - \frac{1}{\theta} \right) k(s_j,q_j) + \frac{1}{\theta} y \left( 1 - \frac{1}{\theta} \right) \left[ z + \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \tau_a^{-1} \right) + \frac{\tau_s}{\tau_a + \tau_s} s_j \right],
\end{align*}

where

\begin{align*}
    \mathbb{E} \left[ \varepsilon_j|s_j,q_j \right] &= \frac{\tau_e}{\tau_e + \tau_q} \left( -\frac{1}{2} \tau_e^{-1} \right) + \frac{\tau_q}{\tau_e + \tau_q} \tilde{q}_j, \\
    \text{Var}[v_j|s_j,q_j] &= \left( \frac{1}{\theta} \right)^2 \text{Var} \left[ \varepsilon_j|s_j,q_j \right] + \left( 1 - \frac{1}{\theta} \right)^2 \frac{1}{\tau_a + \tau_s},
\end{align*}

where \( \text{Var} \left[ \varepsilon_j|s_j,q_j \right] = \frac{1}{\tau_e + \tau_q} \).

Therefore, the market clearing condition, (7), implies

\begin{equation}
0 = n_j + \lambda - \frac{1}{\theta} \left[ \frac{\tau_e}{\tau_e + \tau_s + \tau_q} \left( -\frac{1}{2} \tau_e^{-1} \right) \varepsilon_j + \frac{\tau_q}{\tau_e + \tau_s + \tau_q} \tilde{q}_j \right] + \eta \left( 1 - \frac{1}{\theta} \right) k(s_j,q_j) + \frac{1}{\theta} y + \left( 1 - \frac{1}{\theta} \right) \left[ \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \tau_a^{-1} \right) + \frac{\tau_s}{\tau_a + \tau_s} s_j + z \right] - q_j
\end{equation}

\begin{equation}
0 = n_j + \lambda - \frac{\gamma}{\theta} \left[ \frac{1}{\tau_e + \tau_s + \tau_q} + \left( 1 - \frac{1}{\theta} \right)^2 \right] + \eta \left( 1 - \frac{1}{\theta} \right) k(s_j,q_j) + \frac{1}{\theta} y + \left( 1 - \frac{1}{\theta} \right) \left[ \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \tau_a^{-1} \right) + \frac{\tau_s}{\tau_a + \tau_s} s_j + z \right] - q_j
\end{equation}

\begin{equation}
0 = n_j + \lambda - \frac{1}{\theta} \left( \frac{\tau_e}{\tau_e + \tau_s + \tau_q} \left( -\frac{1}{2} \tau_e^{-1} \right) + \frac{\tau_q}{\tau_e + \tau_s + \tau_q} \tilde{q}_j \right) + \eta \left( 1 - \frac{1}{\theta} \right) k(s_j,q_j) + \frac{1}{\theta} y + \left( 1 - \frac{1}{\theta} \right) \left[ \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \tau_a^{-1} \right) + \frac{\tau_s}{\tau_a + \tau_s} s_j + z \right] - q_j
\end{equation}

\begin{equation}
0 = n_j + \lambda - \frac{\gamma}{\theta} \left[ \frac{1}{\tau_e + \tau_s + \tau_q} + \left( 1 - \frac{1}{\theta} \right)^2 \right] + \eta \left( 1 - \frac{1}{\theta} \right) k(s_j,q_j) + \frac{1}{\theta} y + \left( 1 - \frac{1}{\theta} \right) \left[ \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \tau_a^{-1} \right) + \frac{\tau_s}{\tau_a + \tau_s} s_j + z \right] - q_j.
\end{equation}
It is straightforward to see that (B.2) can be transformed to

\[ f(s_j, q_j, y, z) + \lambda \frac{1}{\beta} \frac{t_x}{\tau_{x} + \tau_{q}} \gamma \left[ \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_{x} + \tau_{q}} + (1 - \frac{1}{\beta}) \frac{1}{\tau_{a} + \tau_{e}} \right] \varepsilon_j + n_j = 0, \]

where \( f(s_j, q_j, y, z) \) is a linear function of \( s_j, q_j, y \) and \( z \). Hence,

\[ \beta_3 = \gamma \left[ \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_{x} + \tau_{q}} + (1 - \frac{1}{\beta}) \frac{1}{\tau_{a} + \tau_{e}} \right], \]

which, by substituting \( \tau_q^{-1} = \beta_3^2 \tau_n^{-1} \), implies

\[ \frac{\lambda}{\beta} \left[ (\tau_{a} + \tau_{e}) \tau_x \right] \beta_3^3 - \gamma \left[ \left( \frac{1}{\beta} \right)^2 \left( \tau_{x} + \tau_{q} \right) + \left( 1 - \frac{1}{\beta} \right) (\tau_{a} + \tau_{x}) \right] \beta_3^2 - \gamma \left( 1 - \frac{1}{\beta} \right)^2 \tau_n = 0. \]  

(B.3) clearly has a unique positive solution with respect to \( \beta_3 \). In fact, if we write the LHS of (B.3) as function \( \Lambda(\beta_3) \), it is easy to show that equation \( \Lambda(\beta_3) + \gamma (1 - \frac{1}{\beta})^2 \tau_n = 0 \) has a unique positive solution. Hence, equation \( \Lambda(\beta_3) = 0 \) has a unique positive solution, around which \( \frac{\partial \Lambda}{\partial \beta_3} > 0 \). We also prove that the unique positive solution of \( \beta_3 \) is decreasing in \( \lambda \). In fact, \( \frac{\partial \Lambda}{\partial \beta_3} > 0 \) and \( \frac{\partial \Lambda}{\partial \lambda} = \frac{\lambda}{\beta} \left[ (\tau_{a} + \tau_{e}) \tau_x \right] \beta_3^3 > 0 \), so \( \frac{\partial \beta_3}{\partial \lambda} = -\frac{\partial \Lambda}{\partial \beta_3} < 0 \). Also, the unique positive solution of \( \beta_3 \) is decreasing in \( \tau_e \). In fact, \( \frac{\partial \Lambda}{\partial \tau_e} = \frac{\lambda}{\beta} \tau_x \beta_3^3 - \gamma \left( \frac{1}{\beta} \right)^2 \beta_3^2 = \frac{\gamma (1 - \frac{1}{\beta})^2 (\tau_{x} + \tau_{q}) \beta_3^2 + \gamma (1 - \frac{1}{\beta})^2 \tau_n}{\tau_{a} + \tau_{e}} > 0 \), where the second equality is due to (B.3), so \( \frac{\partial \beta_3}{\partial \tau_e} = -\frac{\partial \Lambda}{\partial \beta_3} < 0 \) (or \( \frac{dr_e}{dr_e} > 0 \)).

**Proof of Lemma 2:** The first-order condition of (4) implies

\[ K_j = K(s_j, \bar{q}_j) = \left[ \eta \left( 1 - \frac{1}{\theta} \right) Y_j Z^{1-\frac{1}{\theta}} \right] \Theta \left( E\left[ x_j^{\frac{1}{\theta}} A_j^{1-\frac{1}{\theta}} \right] | s_j, \bar{q}_j \right) \]

where \( \Theta = -\frac{1}{\eta \left( 1 - \frac{1}{\theta} \right) - 1} \in (1, \theta) \). Combining (1), (2), and (B.4), we have

\[
\pi(a_j, \varepsilon_j, s_j, \bar{q}_j) = P_j(\varepsilon_j, Y_j) Y_j(a_j, K_j) - K_j(s_j, \bar{q}_j) = \left\{ \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{-1} \left( Y_j Z^{1-\frac{1}{\theta}} \right)^{\Theta} \left( E\left[ x_j^{\frac{1}{\theta}} A_j^{1-\frac{1}{\theta}} \right] | s_j, \bar{q}_j \right) \right\}^{\Theta \left( 1 - \frac{1}{\theta} \right)},
\]
Thus,

\[ \mathbb{E} \left[ \pi(a_j, \varepsilon_j, s_j, q_j) | s_j, q_j \right] = \left[ 1 - \eta \left(1 - \frac{1}{\theta} \right) \right] \left[ \eta \left(1 - \frac{1}{\theta} \right) \right]^{\Theta - 1} \left( Y \pi Z^{1 - \frac{1}{\theta}} \right)^{\Theta} \mathbb{E} \left( \epsilon_j^{\frac{1}{\theta}} A_j^{\frac{1}{\theta} - \frac{1}{\sigma}} | s_j, q_j \right) \Theta . \]

We have

\[
\log \mathbb{E} \left[ \epsilon_j^{\frac{1}{\theta}} A_j^{\frac{1}{\theta} - \frac{1}{\sigma}} | s_j, q_j \right] = \frac{1}{\theta} \left[ \frac{\tau_e}{\tau_e + \tau_q} \left( -\frac{1}{2} \right)^{\tau_e - 1} + \frac{\tau_q}{\tau_e + \tau_q} \left( \frac{1}{2} \right)^{\tau_q - 1} \right] + \frac{1}{2} - 1 \left[ \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \right)^{\tau_a - 1} + \frac{\tau_s}{\tau_a + \tau_s} \right] + \frac{1}{2} \left( 1 - \frac{1}{\theta} \right)^{\tau_e + \tau_q} + \frac{1}{2} \left( 1 - \frac{1}{\theta} \right)^{\tau_a + \tau_s} .
\]

So

\[
\phi_0' = \Theta \log \left[ \eta \left(1 - \frac{1}{\theta} \right) \right] + \frac{\Theta}{\theta} y + \left( 1 - \frac{1}{\theta} \right) \Theta \log Z + \frac{\Theta}{\theta} \left[ \frac{\tau_e}{\tau_e + \tau_q} \left( -\frac{1}{2} \right)^{\tau_e - 1} \right] + \left( 1 - \frac{1}{\theta} \right) \Theta \left( \frac{1}{\theta} \right)^{\tau_e + \tau_q} + \frac{1}{2} \Theta \left( \frac{1}{\theta} \right)^{\tau_a + \tau_s} + \frac{1}{2} \Theta \left( 1 - \frac{1}{\theta} \right)^{\tau_a + \tau_s} .
\]

In addition,

\[
\mathbb{E} \exp \left\{ \frac{\Theta}{\theta} \left[ \frac{\tau_e}{\tau_e + \tau_q} \left( -\frac{1}{2} \right)^{\tau_e - 1} + \frac{\tau_q}{\tau_e + \tau_q} \left( \frac{1}{2} \right)^{\tau_q - 1} \right] + \frac{\Theta}{\theta} \left( 1 - \frac{1}{\theta} \right) \left[ \frac{\tau_a}{\tau_a + \tau_s} \left( -\frac{1}{2} \right)^{\tau_a - 1} + \frac{\tau_s}{\tau_a + \tau_s} \right] \right\}
\]

\[
= \exp \left\{ \frac{\Theta}{\theta} \left[ \left( -\frac{1}{2} \right)^{\tau_e - 1} \right] + \frac{1}{2} \left( \frac{\Theta}{\theta} \right)^2 \left( \frac{\tau_q}{\tau_e + \tau_q} \right)^{\tau_q - 1} \right\} + \left( \frac{\Theta}{\theta} \right)^2 \left( \frac{\tau_a}{\tau_a + \tau_s} \right)^{\tau_a - 1} \right\}
\]

Thus,

\[
\mathbb{E} \left( \mathbb{E} \left( A_j^{\frac{1}{\theta}} \epsilon_j^{\frac{1}{\theta}} | s_j, q_j \right) \right)^\Theta = \exp \left\{ \frac{1}{2} \left\{ \left[ \Theta (1 - \frac{1}{\theta}) \right] - \Theta (1 - \frac{1}{\theta}) \right\} \frac{1}{\tau_a} + \frac{1}{2} \left( \frac{\Theta}{\theta} \right)^2 \left( 1 - \frac{1}{\theta} \right)^{\tau_a + \tau_s} \right\} .
\]

It is easy to show that $\frac{\partial \Pi}{\partial \tau_s} > 0$ and $\frac{\partial \Pi}{\partial \tau_q} > 0$, by noting that

\[
\sgn \left( \frac{\partial \Pi}{\partial \tau_s} \right) = \sgn \left\{ \exp \left\{ \Theta (1 - \frac{1}{\theta}) \left( \frac{1}{2} \right)^{\tau_a + \tau_s} + \frac{1}{2} \left( \frac{1}{\theta} \right)^2 \left( 1 - \frac{1}{\theta} \right)^{\tau_a + \tau_s} \right\} \right\} .
\]
Moreover, \( \frac{\partial^2 \Pi}{\partial \tau_s \partial \tau_q} > 0 \), by noting that

\[
sgn \left( \frac{\partial^2 \Pi}{\partial \tau_s \partial \tau_q} \right) = sgn \left\{ \exp \left\{ -\Theta (\Theta - 1) \left[ \frac{1}{2} (1 - \frac{1}{\beta})^2 \frac{1}{\tau_s + \tau_q} + \frac{1}{2} (\frac{1}{\beta})^2 \frac{1}{\tau_s + \tau_q} \right] \right\} \cdot \left[ \Theta (\Theta - 1) \left( \frac{1}{2} (\frac{1}{\beta})^2 \frac{1}{(\tau_s + \tau_q)^2} \right) \right] \left[ \Theta (\Theta - 1) \left( \frac{1}{2} (1 - \frac{1}{\beta})^2 \frac{1}{(\tau_s + \tau_q)^2} \right) \right] \}.
\] (B.5)

Finally, it is easy to show that \( \frac{\partial^2 \Pi}{\partial \tau_s \partial Y} > 0 \) and \( \frac{\partial^2 \Pi}{\partial \tau_q \partial Z} > 0 \).

**Proof of Proposition 1:** The proof is quite similar to that in Grossman and Stiglitz (1980). By the definition \( EV(W^i) \equiv \mathbb{E} [U(W^i)|s_j, q_j] \), we have \( \frac{EV(W^{fi})}{EV(W^{ui})} = e^{\gamma_c} \sqrt{\frac{Var[v_j|s_j, q_j]}{Var[v_j|s_j, q_j]}} \). Thus,

\[
\frac{EV(W^{fi})}{EV(W^{ui})} = 1 \iff \sqrt{\frac{(1 - \frac{1}{\beta})^2 \frac{1}{\tau_s + \tau_q} + \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q}}{(1 - \frac{1}{\beta})^2 \frac{1}{\tau_s + \tau_q} + \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q}}} = e^{\gamma_c}.
\] (B.6)

Let \( F(\tau_q; \tau_s) = \frac{(1 - \frac{1}{\beta})^2 \frac{1}{\tau_s + \tau_q} + \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q}}{(1 - \frac{1}{\beta})^2 \frac{1}{\tau_s + \tau_q} + \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q}} \), which implies

\[
\frac{\partial F}{\partial \tau_s} = -\left( 1 - \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q} + \frac{\left( \frac{1}{\beta} \right)^2}{\tau_s + \tau_q} - \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q} \left( 1 - \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q} < 0
\]

and

\[
\frac{\partial F}{\partial \tau_q} = \left\{ \left( \frac{1}{\beta} \right)^2 \frac{1}{\tau_s + \tau_q} \left[ \frac{1}{\tau_s + \tau_q} \left( \frac{1}{\tau_s + \tau_q} \right) - \frac{1}{\tau_s + \tau_q} \right] \right\} > 0.
\]

Because \( F(\tau_q; \tau_s) = e^{-2\gamma_c} \), by the implicit function theorem, we have \( \frac{\partial \tau_q}{\partial \tau_s} = -\frac{\partial F}{\partial \tau_s} / \partial \tau_q > 0 \). Also, by \( \frac{\partial F}{\partial \tau_q} > 0 \), we have \( \frac{\partial \tau_q}{\partial \tau_s} < 0 \).

**Proof of Proposition 2:** Because \( \frac{\partial \Pi}{\partial \tau_s} > 0 \), we have \( \Pi(\tau_s = \bar{\tau}_s; \tau_q, Y, Z) - \Pi(\tau_s = \bar{\tau}_s; \tau_q, Y, Z) > 0 \) for a given \( \tau_q, Y \) and \( Z \). Because \( \frac{\partial^2 \Pi}{\partial \tau_s \partial \tau_q} > 0 \), there exists a unique \( \tau_q \) such that

\[
\Pi(\tau_s = \bar{\tau}_s; \tau_q, Y, Z) - \Pi(\tau_s = \bar{\tau}_s; \tau_q, Y, Z) = b.
\] (B.7)

Denote the LHS of (B.7) by function \( \Gamma(\tau_q, Y, Z) \) for a given \( \tau_q \) and \( \bar{\tau}_s \). Because \( \frac{\partial^2 \Pi}{\partial \tau_s \partial \tau_q} > 0 \), \( \frac{\partial^2 \Pi}{\partial \tau_s \partial \tau_q} > 0 \), and \( \frac{\partial^2 \Pi}{\partial \tau_q \partial Y} > 0 \), we have that \( \frac{\partial \tau_q}{\partial \tau_s} > 0 \), \( \frac{\partial \tau_q}{\partial \tau_q} > 0 \), and \( \frac{\partial \tau_q}{\partial Y} > 0 \). Therefore, by the implicit function theorem, we have that \( \frac{\partial \tau_q(Y, Z, b)}{\partial Y} = -\frac{\partial \tau_q(Y, Z, b)}{\partial \tau_s} < 0 \), \( \frac{\partial \tau_q(Y, Z, b)}{\partial \tau_s} = -\frac{\partial \tau_q(Y, Z, b)}{\partial \tau_q} < 0 \), and \( \frac{\partial \tau_q(Y, Z, b)}{\partial \tau_q} > 0 \).
Proof of Proposition 3: By (16), the condition that guarantees \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_q^*)\) is one equilibrium is \(\tau_q^* \leq \hat{\tau}_q(Y, Z, b)\). Similarly, the condition that guarantees \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_q^{**})\) is one equilibrium is \(\tau_q^{**} \geq \hat{\tau}_q(Y, Z, b)\). Considering that \(\hat{\tau}_q(Y, Z, b)\) can be of the three cases: \(\hat{\tau}_q > \tau_q^{**}\), \(\hat{\tau}_q \leq \tau_q^{**}\), and \(\hat{\tau}_q < \tau_q^{**}\), it is straightforward to obtain Proposition 3.

Figure B.1 graphically illustrates the full comparative statics — the parameter regions of \((Y, Z, b, c)\) for a particular type of equilibrium to prevail, where the threshold curve \(\Psi(\cdot; \tau_q)\), given by (17) with \(\hat{\tau}_q\) being replaced by \(\tau_q\), represents \(b\) as a function of \(Y^\frac{1}{2} Z^{1-\frac{1}{2}}\) parameterized by \(\tau_q\). For a given \(c\), a combination \((b, Y^\frac{1}{2} Z^{1-\frac{1}{2}})\) determines which type of equilibrium will prevail. When \(c\) increases, the two threshold curves rotate clockwise and hence the parameter region of \((b, Y^\frac{1}{2} Z^{1-\frac{1}{2}})\) over which Case 3 of equilibrium prevails shrinks while that over which Case 1 prevails expands.

![Figure B.1. Parameter regions of \((Y, Z, b, c)\) for different equilibrium cases.](image)

Proof of Proposition 4: Substituting (B.4) and (1) into (18) yields

\[
Y = \left[ \int e_j A_j ^\frac{1}{2} \left( Z \left[ \eta \left( 1 - \frac{1}{\theta} \right) Y^\frac{1}{2} Z^{1-\frac{1}{2}} \right]^{\Theta \eta} \left[ \int \left( e_j A_j ^\frac{1}{2} \left( \mathbb{E} \left[ e_j A_j ^\frac{1}{2} | s_j, \tilde{q}_j \right] \right) \right]^{\Theta - 1} \right] \right]^{\frac{\phi - 1}{\varphi - 1}} dj \right]^{\frac{\phi}{\varphi - 1}}
\]

\[
= Z \left[ \eta \left( 1 - \frac{1}{\theta} \right) Y^\frac{1}{2} Z^{1-\frac{1}{2}} \right]^{\Theta \eta} \left[ \int e_j A_j ^\frac{1}{2} \left( \mathbb{E} \left[ e_j A_j ^\frac{1}{2} | s_j, \tilde{q}_j \right] \right) \right]^{\Theta - 1} \right]^{\frac{\phi}{\varphi - 1}}
\]

\[
= Z^{\phi} \left[ \eta \left( 1 - \frac{1}{\theta} \right) Y^\frac{1}{2} \right]^{\Theta \eta} \left[ \int e_j A_j ^\frac{1}{2} \left( \mathbb{E} \left[ e_j A_j ^\frac{1}{2} | s_j, \tilde{q}_j \right] \right) \right]^{\Theta - 1} \right]^{\frac{\phi}{\varphi - 1}}
\]

where the last equality follows based on \(\Theta = -\frac{1}{\eta(1-\theta)-1}\).
Exploiting the law of iterated expectations, we have
\[
\int \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta - 1} dj = \mathbb{E} \left[ \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta} \right].
\]

Hence, (B.8) becomes
\[
Y = Z^{\Theta \frac{\theta}{\theta - \eta}} \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta \eta \frac{\theta}{\theta - \eta}} \left\{ \mathbb{E} \left[ \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta} \right] \right\}^{\frac{\theta}{\theta - \eta} - \eta}. \tag{B.9}
\]

Similarly, the aggregate investment in the economy is given by
\[
K = \int K_j dj = \left[ \eta \left( 1 - \frac{1}{\theta} \right) Y^\frac{1}{\theta} Z^{1 - \frac{1}{\theta}} \right]^{\Theta} \left\{ \mathbb{E} \left[ \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta} \right] \right\}
\]
\[
= Z^{(1 - \frac{1}{\theta})\Theta + \Theta \frac{\theta}{\theta - \eta} \frac{\frac{\theta}{\theta - \eta}}{\Theta}} \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta \eta \frac{\theta}{\theta - \eta} + \Theta} \left\{ \mathbb{E} \left[ \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta} \right] \right\}^{\frac{\theta}{\theta - \eta} - \eta + 1}.
\]

where the second equality is obtained by substituting the expression of $Y$ into (B.9). Because
\[
\Theta \frac{\theta}{\theta - \eta} - \left[ (1 - \frac{1}{\theta}) \Theta + \Theta \frac{\theta}{\theta - \eta} \frac{\frac{\theta}{\theta - \eta}}{\Theta} \right] \eta = 1, \quad \text{and} \quad \Theta \eta \frac{\theta}{\theta - \eta} + \Theta = \frac{\theta}{\theta - \eta} \Theta \quad \text{(that is,} \quad \Theta \eta \frac{\theta}{\theta - \eta} = \left( \Theta \eta \frac{\theta}{\theta - \eta} + \Theta \right) \eta) \quad \text{and} \quad \frac{\theta}{\theta - \eta} \frac{\theta}{\theta - \eta} + 1 \eta = \frac{\theta}{\theta - \eta} - \eta, \quad \text{it follows that} \quad Y = Z A K^\eta, \quad \text{where} \quad A = A(\tau_s, \tau_q) \quad \text{is given by}
\]
\[
A(\tau_s, \tau_q) = \left\{ \mathbb{E} \left[ \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta} \right] \right\}^{\frac{\theta}{\theta - \eta}}
\]
\[
= \exp \left\{ \left( \frac{\theta}{\theta - 1} - \eta \right) \left( \Theta (1 - \frac{1}{\theta}) \left( \frac{1}{\tau_s} + \frac{1}{2} \left[ \Theta (1 - \frac{1}{\theta}) \right]^2 + \frac{1}{\tau_q} + \Theta \left( \frac{1}{\theta} - \frac{1}{\tau_s} \right)^2 \left( \frac{1}{\theta} - \frac{1}{\tau_q} \right)^2 \right) \right\}.
\]

Because $0 < \eta < 1$ and thus $\frac{\theta}{\theta - 1} - \eta > 0$, $A(\tau_s, \tau_q)$ is increasing in $\tau_s$ and $\tau_q$.

Also, we can express $K$ in terms of $A$. In fact,
\[
K = \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta} Z^{(1 - \frac{1}{\theta})} \left\{ \mathbb{E} \left[ \left( \mathbb{E} \left[ \epsilon_j^\frac{1}{\theta_j} A_j^{1 - \frac{1}{\theta_j}} | s_j, \bar{q}_j \right] \right)^{\Theta} \right] \right\} \cdot Y^\frac{\rho}{\theta}
\]
\[
= \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta} Z^{(1 - \frac{1}{\theta})} A^{\frac{1}{\theta - \eta} + \frac{\theta}{\theta - \eta}} \left( Z A K^\eta \right)^\frac{1}{\theta - \eta} = \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta} Z^{(1 - \frac{1}{\theta})} A^{-\frac{1}{\theta - \eta} + \frac{\theta}{\theta - \eta}} K^{-\frac{\theta}{\theta - \eta}}.
\]

This implies that $K^{1 - \eta} A^\frac{1}{\theta - \eta} + \frac{\theta}{\theta - \eta} = \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta} Z A^\frac{1}{\theta - \eta} + \frac{\theta}{\theta - \eta}$, which means
\[
K = \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta} A^{\frac{1}{\theta - \eta} + \frac{\theta}{\theta - \eta}} \left( Z A K^\eta \right)^{\frac{1}{\theta - \eta}} \quad \text{or} \quad K = \left[ \eta \left( 1 - \frac{1}{\theta} \right) \right]^{\Theta} A^{\frac{1}{\theta - \eta} + \frac{\theta}{\theta - \eta}},
\]

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where the last equality is obtained by \( \Theta = -\frac{1}{\eta} - \frac{\eta}{\eta - \frac{1}{\eta}} = -\frac{\eta}{\eta - \frac{1}{\eta}} \) and thus \( \frac{1}{\eta - \frac{1}{\eta}} + \Theta \frac{\eta}{\eta - \frac{1}{\eta}} = \Theta \). Because \( 0 < \eta < 1 \) and \( \Theta \in (1, \Theta) \), \( K \) is increasing in \( A \) and thus is increasing in \( \tau_s \) and \( \tau_q \).

Finally, by noting \( \frac{\Theta}{1-\eta_\tau} + 1 = \frac{\Theta}{\eta_\tau} \), we have

\[
Y = ZAK^n = ZA \left[ \eta \left( 1 - \frac{1}{\theta} \right) Z \right]^{\frac{\Theta}{1-\eta_\tau} - \eta} A^{\frac{\Theta}{1-\eta_\tau} - \eta} = \left[ \eta \left( 1 - \frac{1}{\theta} \right) Z \right]^{\frac{\Theta}{1-\eta_\tau} - \eta} . (ZA)^{\frac{\Theta}{1-\eta_\tau} - \eta} .
\]

**Proof of Proposition 5:** Suppose all other islands have the equilibrium \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{q}^*)\). Then, by Propositions 2 and 4, for a given \( b \) and \( c \), the condition of \( Z \) that guarantees \((\bar{\tau}_s, \tau_{q}^*)\) is also one equilibrium on island \( j \) is \( Z = \bar{Z} \), where \( \bar{Z} \) satisfies

\[
\Pi \left( \tau_s = \bar{\tau}_s; \tau_{q}^*, Y (\bar{A}, \bar{Z}), \bar{Z} \right) - \Pi \left( \tau_s = \bar{\tau}_s; \tau_{q}^*, Y (\bar{A}, \bar{Z}), \bar{Z} \right) = b.
\]

Suppose all other islands have the equilibrium \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{q}^*)\). Then, the condition of \( Z \) that guarantees \((\bar{\tau}_s, \tau_{q}^*)\) is also one equilibrium on island \( j \) is \( Z = \bar{Z} \), where \( \bar{Z} \) satisfies

\[
\Pi \left( \tau_s = \bar{\tau}_s; \tau_{q}^*, Y (\bar{A}, \bar{Z}), \bar{Z} \right) - \Pi \left( \tau_s = \bar{\tau}_s; \tau_{q}^*, Y (\bar{A}, \bar{Z}), \bar{Z} \right) = b.
\]

Considering that for a given \( b \) and \( c \), \( Z \) can be one of the three cases: \( Z < \bar{Z} \), \( \bar{Z} \leq Z \leq \bar{Z} \), and \( Z > \bar{Z} \), it is straightforward to obtain Proposition 5.

**Proof of Lemma 3:** By (11) and (23), the ex ante expected profit for an intermediate-goods firm choosing \( \bar{\tau}_s \) for the given \( \tau_q = \tau_{q}^* \), relative to the ex ante expected profit for an “average” intermediate-goods firm, is scaled by \( \left( \frac{A(\tau_s, \tau_{q}^*)}{A} \right)^{\frac{1}{\eta_\tau}} \). Similarly, the ex ante expected profit for an intermediate-goods firm choosing \( \tau_s \) for the given \( \tau_q = \tau_{q}^* \), relative to the ex ante expected profit for an “average” intermediate-goods firm, is scaled by \( \left( \frac{A(\tau_s, \tau_{q}^*)}{A} \right)^{\frac{1}{\eta_\tau}} \). It is easy to show that the ex ante expected profit for an “average” intermediate-goods firm in the economy is \( \frac{1}{b} Y \). Then, we can define a threshold \( b^* \), given by (32). This implies that when \( b_j \geq b^* \), \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{q}^*)\) is one equilibrium for island \( j \). By a similar argument, when \( b_j \leq b^{**} \), \((\tau_s, \tau_q) = (\bar{\tau}_s, \tau_{q}^*)\) is one equilibrium for island \( j \). Given \( b^* \) and \( b^{**} \), we can divide all islands into three types: \( b_j < b \), \( b^* \leq b_j \leq b^{**} \), and \( b_j > b^{**} \). Lemma 3 thus follows.

**Proof of Proposition 6:** Suppose an equilibrium is already found in which \( \omega \) satisfies \( G(b^*) < \omega < G(b^{**}) \). Then a slight increase in \( \omega \) to \( \omega^+ \) must be another equilibrium because \( G(b^*) < \omega^+ < G(b^{**}) \). For the corner case, if an equilibrium satisfies \( G(b^*) = \omega < G(b^{**}) \), it is easy to show that \( \omega^+ \) or \( \omega^- \) must be another equilibrium because either \( G(b^*) < \omega^+ < G(b^{**}) \) or \( G(b^-) < \omega^- < G(b^{**}) \) must hold. A similar argument applies to the corner case of \( G(b^*) < \omega = G(b^{**}) \).
Proof of Lemma 4: The first-order conditions of (37) imply that

\[
\eta (1 - \frac{1}{\theta}) N_j t^{(1-\eta)(1-\frac{1}{\theta})} K_j t^{(1-\frac{1}{\theta})-1} Z_j t^{-\frac{1}{\theta}} Y_j t^{\frac{1}{\theta}} \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] = R_t,
\]

\[
(1 - \eta)(1 - \frac{1}{\theta}) N_j t^{(1-\eta)(1-\frac{1}{\theta})-1} K_j t^{(1-\frac{1}{\theta})} Z_j t^{-\frac{1}{\theta}} Y_j t^{\frac{1}{\theta}} \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] = W_t,
\]

(B.10)

which means \( \frac{R_t K_j t}{W_t N_j t} = \frac{\eta}{1 - \eta} \). Hence, in aggregate, \( R_t K_t = (1 - \frac{1}{\theta})\eta Y_t \) and \( W_t N_t = (1 - \frac{1}{\theta})(1 - \eta)Y_t \), where \( \int_0^1 K_j t dj = K_t \) and \( \int_0^1 N_j t dj = N_t = 1 \). Plugging \( \frac{R_t K_j t}{W_t N_j t} = \frac{\eta}{1 - \eta} \) into (B.10), we have

\[
K_j t \propto \left\{ \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] \right\}^\theta \quad \text{and} \quad N_j t \propto \left\{ \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] \right\}^\theta .
\]

Hence, we also have the following resource allocation across firms (entrepreneurs):

\[
K_j t = \frac{\left\{ \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] \right\}^\theta - K_t}{\int_0^1 \left\{ \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] \right\}^\theta dj} \quad \text{and} \quad N_j t = \frac{\left\{ \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] \right\}^\theta - N_t}{\int_0^1 \left\{ \mathbb{E} \left[ A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right] \right\}^\theta dj} .
\]

(B.11)

Substituting (35) and (B.11) into (36), we have the aggregate production function: \( Y_t = Z_t A_t \left( K_t^{\eta} N_t^{1-\eta} \right) \), where

\[
A_t = A(\tau_{st}, \tau_{qt}) = \mathbb{E} \left( \left[ \mathbb{E} \left( A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right) \right]^\theta \right)^{\frac{\theta}{\theta - 1}} = \exp \left( \frac{\theta - 2}{2 \tau_a} - \frac{(\theta - 1)^2}{2 \theta} \frac{1}{\tau_a + \tau_{st}} - \frac{1}{2 \theta (\tau_a + \tau_{qt})} \right) .
\]

Proof of Proposition 7: Similar to (11), an entrepreneur’s ex ante expected profit is proportional to \( \mathbb{E} \left( \left[ \mathbb{E} \left( A_j t^{-\frac{1}{\theta}} e_j t^{\frac{1}{\theta}} | I_j \right) \right]^\theta \right)^{\theta - 1} \) or \( A(\tau_{st}, \tau_{qt})^{\theta - 1} \). Suppose that all other islands have equilibrium \( (\tau_{st}, \tau_{qt}) = (\tau_s, \tau_q^*) \) and the financial market equilibrium on island \( j \) is \( \tau_{qt} = \tau_q^* \). Then, the expected profit for the entrepreneur on island \( j \) to choose \( \tau_{st} = \tau_s \) is \( 1/\theta Y(Z_t, A, K_t) \) and the expected profit to choose \( \tau_{st} = \tau_s^* \) is \( 1/\theta Y(Z_t, A, K) \). Thus, the condition of \( K_t \) that guarantees the entrepreneur on island \( j \) chooses \( \tau_{st} = \tau_s^* \) is \( K_t < \tilde{K} \), where \( \tilde{K} \) satisfies

\[
\frac{1}{\theta} Y(Z_t, A, \tilde{K}) - b = \frac{1}{\theta} Y(Z_t, A, K) .
\]

That is, when \( K_t < \tilde{K} \), \( (\tau_{st}, \tau_{qt}) = (\tau_s, \tau_q^*) \) is one equilibrium for all islands. Similarly, suppose that all other islands have equilibrium \( (\tau_{st}, \tau_{qt}) = (\tau_s^*, \tau_q^*) \) and the financial market equilibrium on island \( j \) is \( \tau_{qt} = \tau_q^* \). Then, the condition of \( K_t \) that guarantees that the entrepreneur on island \( j \) chooses \( \tau_{st} = \tau_s \) is \( K_t > \tilde{K} \), where \( \tilde{K} \) satisfies

\[
\frac{1}{\theta} Y(Z_t, A, \tilde{K}) - b = \frac{1}{\theta} Y(Z_t, A, K) .
\]
That is, when \( K_t > K_* \), \((\tau_{st}, \tau_{gt}) = (\bar{\tau}_s, \bar{\tau}_v)\) is one equilibrium for all islands. It is easy to show that both \( \bar{K} \) and \( K \) are decreasing functions of \( Z_t \). Considering that \( K_t \) can be one of the three cases: \( K_t > \bar{K}, \bar{K} \leq K_t \leq \bar{K}, \) and \( K_t < \bar{K}, \) it is straightforward to obtain Proposition 7.

**Proof of Proposition 8:** By (38), we can find the steady-state \( K \), which is given by

\[
K = \begin{cases} 
[(1 - \frac{1}{\theta})(1 - \eta)ZA]^{\frac{1}{1-\eta}} & \text{if } K \geq \bar{K}(Z) \\
[(1 - \frac{1}{\theta})(1 - \eta)ZA]^{\frac{1}{1-\eta}} & \text{if } K \leq \bar{K}(Z)
\end{cases}
\]

We can also find \( \bar{K} = \left( \frac{b \theta}{T - 1} \right)^{\frac{1}{\eta}} (ZA)^{-\frac{1}{\eta}} \) and \( \bar{K} = \left( \frac{b \theta}{1 - \frac{1}{\xi}} \right)^{\frac{1}{\eta}} (Z \bar{A})^{-\frac{1}{\eta}} \). Clearly, \( \bar{K} > \bar{K} \) when \( \xi \bar{A} < \bar{A} \). It follows that

\[
[(1 - \frac{1}{\theta})(1 - \eta)ZA]^{\frac{1}{1-\eta}} \leq \left( \frac{b \theta}{T - 1} \right)^{\frac{1}{\eta}} (Z \bar{A})^{-\frac{1}{\eta}} \Rightarrow Z \leq Z^{**}
\]

and

\[
[(1 - \frac{1}{\theta})(1 - \eta)ZA]^{\frac{1}{1-\eta}} \geq \left( \frac{b \theta}{1 - \frac{1}{\xi}} \right)^{\frac{1}{\eta}} (Z \bar{A})^{-\frac{1}{\eta}} \Rightarrow Z \geq Z^*
\]

where \( Z^* = \left( \frac{b \theta}{T - 1} \right)^{1-\eta} (\bar{A})^{-\frac{1}{\eta}} \) and \( Z^{**} = \left[ \frac{b \theta}{T - 1} \right]^{1-\eta} (Z \bar{A})^{\frac{1}{1-\eta}} \). Clearly, \( Z^* < Z^{**} \) when \( \xi^{1-\eta} \bar{A} < \bar{A} \).

We have three cases of \( Z \). If \( Z > Z^{**} \), there is a unique steady-state equilibrium, in which \( K^{**} = \frac{1}{1-\theta}(1 - \eta)ZA \). When \( Z < Z^* \), there is a unique steady-state equilibrium, in which \( K^* = \left( \frac{b \theta}{1 - \frac{1}{\xi}} \right)^{1-\eta} (Z \bar{A})^{\frac{1}{1-\eta}} \). If \( Z^* \leq Z \leq Z^{**} \), there are two steady-state equilibria, in which both \( K \) above are possible.

**Proof of Proposition 9:** Because initially \( Z_t = Z > Z^{**} \), the economy has a unique “good” steady-state equilibrium and \( K^{**}(Z) > \bar{K}(Z) \), where \( K^{**}(\cdot) \) is defined in the proof of Proposition 8. Immediately after the shock the capital is still in \( K^{**}(Z) \), but \( Z_t \) becomes \( Z_t = Z^t < Z \). If \( Z^t > Z^{**} \), there is still a unique “good” steady-state equilibrium and the transitional path is unique. Now we examine the case in which \( Z^* < Z^t < Z^{**} \). On the one hand, if \( Z^t \in (Z^*, Z^{**}) \) is not too low, the capital immediately after the shock satisfies the condition \( K_t = K^{**}(Z) > \bar{K}(Z^t) \), by noting that the condition that \( K^{**}(Z) > \bar{K}(Z^t) \) is certainly true if \( Z^t \) is sufficiently close to \( Z^{**} \). This means that immediately after the shock, the transitional path is unique. On the other hand, if \( Z^t \in (Z^*, Z^{**}) \) is not too high, the condition \( K^{**}(Z^t) < \bar{K}(Z^t) \) is true by noting that this condition is certainly true if \( Z^t \) is sufficiently close to \( Z^* \). This means that the dynamics of \( K_t \) enter the region of \( K_t \leq \bar{K}(Z^t) \) before reaching the new “good” steady state \( K^{**}(Z^t) \) and thus the transitional path has two branches after capital declines to \( K_t \leq \bar{K}(Z^t) \).
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